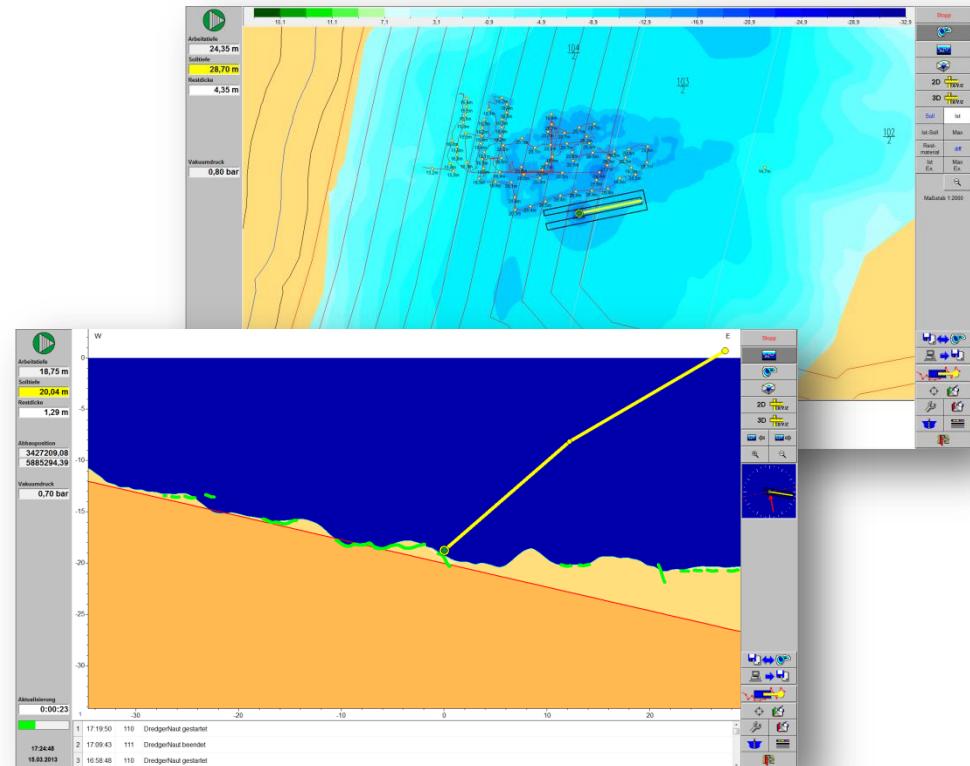


DredgerNaut



Instructions for use

Operate • document • measure



Version: 10-5-1

Status: 23/06/16

www.dredgertec.de



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1 Introduction

DredgerNaut is a measuring and visualization system for the positioning of excavation devices and the continuous documentation of mining operations in sand and gravel mines.

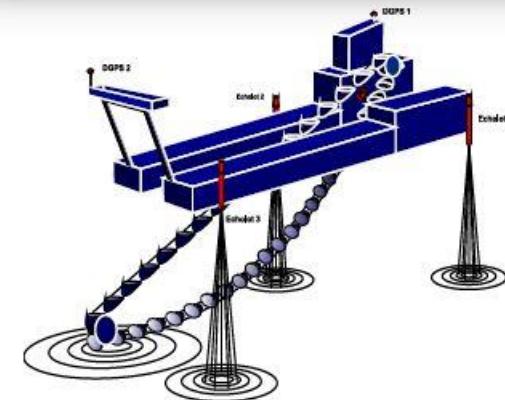
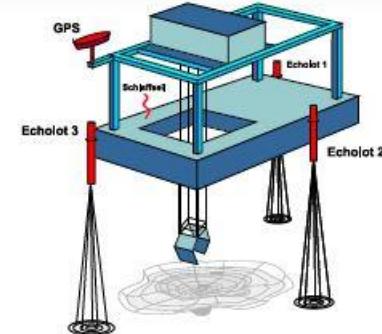
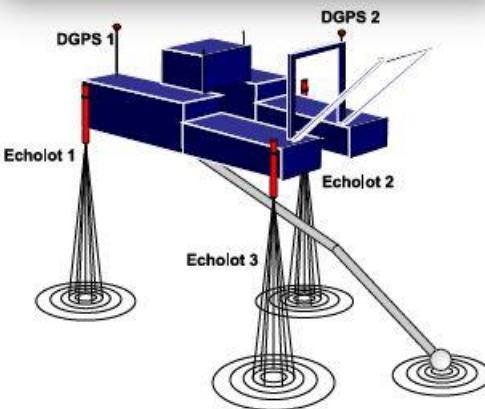
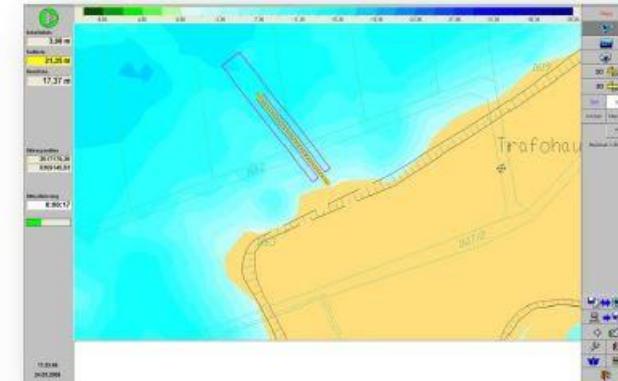
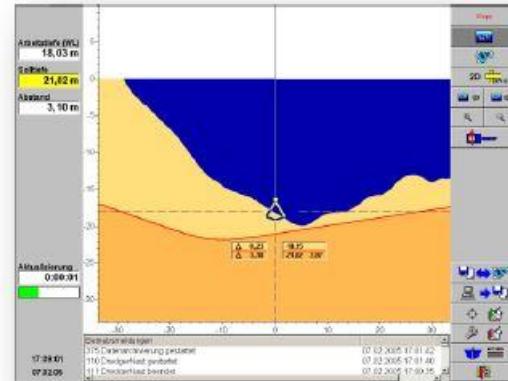
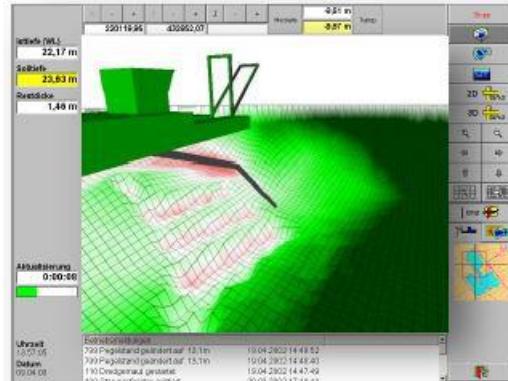


Figure 1-1: Excavation devices

2 DredgerNaut Manager

The **DredgerNaut Manager** is used for the administration and organization of these data on the Central Station. With the **DredgerNaut Manager** it is possible to administer different excavation sites, transfer and activate archive-data, prepare Copies (planning-data) and merge data sets (*Insert*).

Main operations



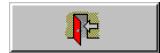
Start



Transfer and activate, if applicable



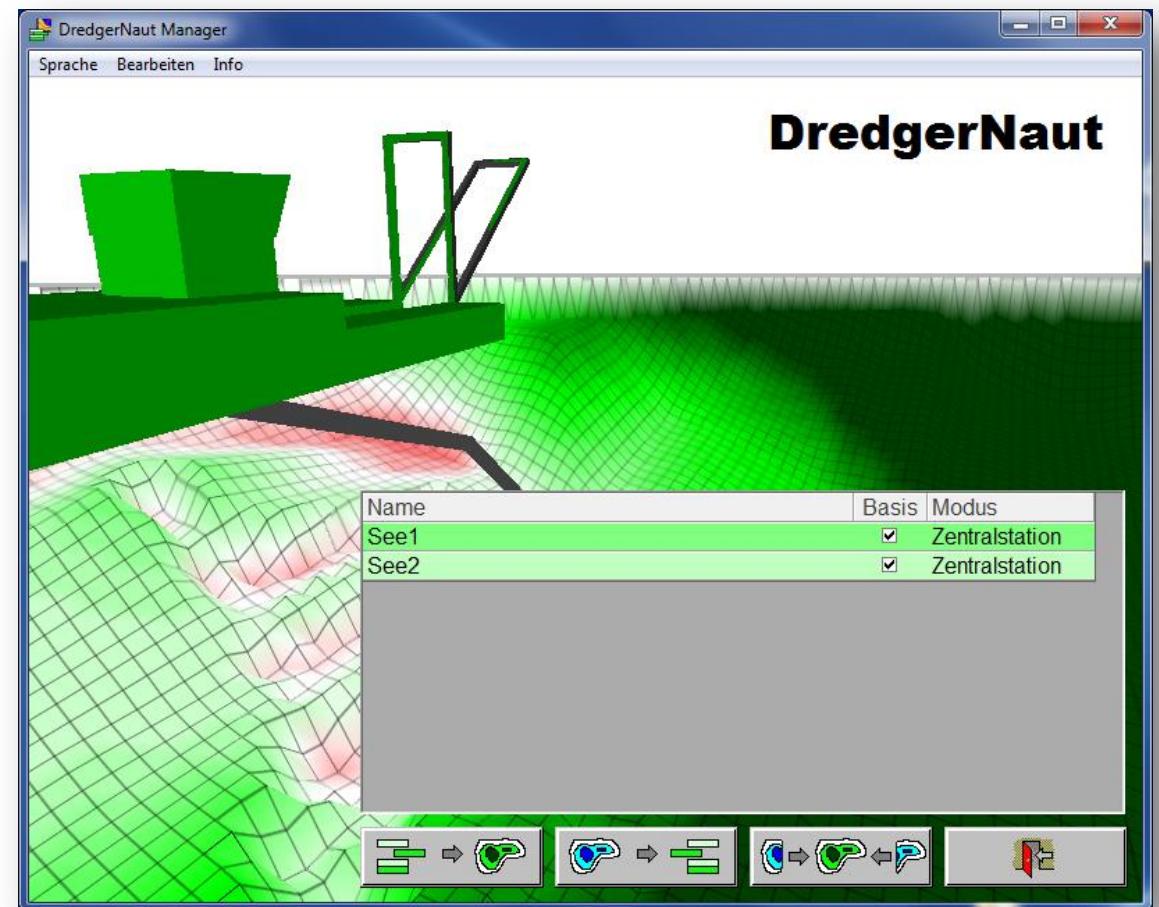
Insert



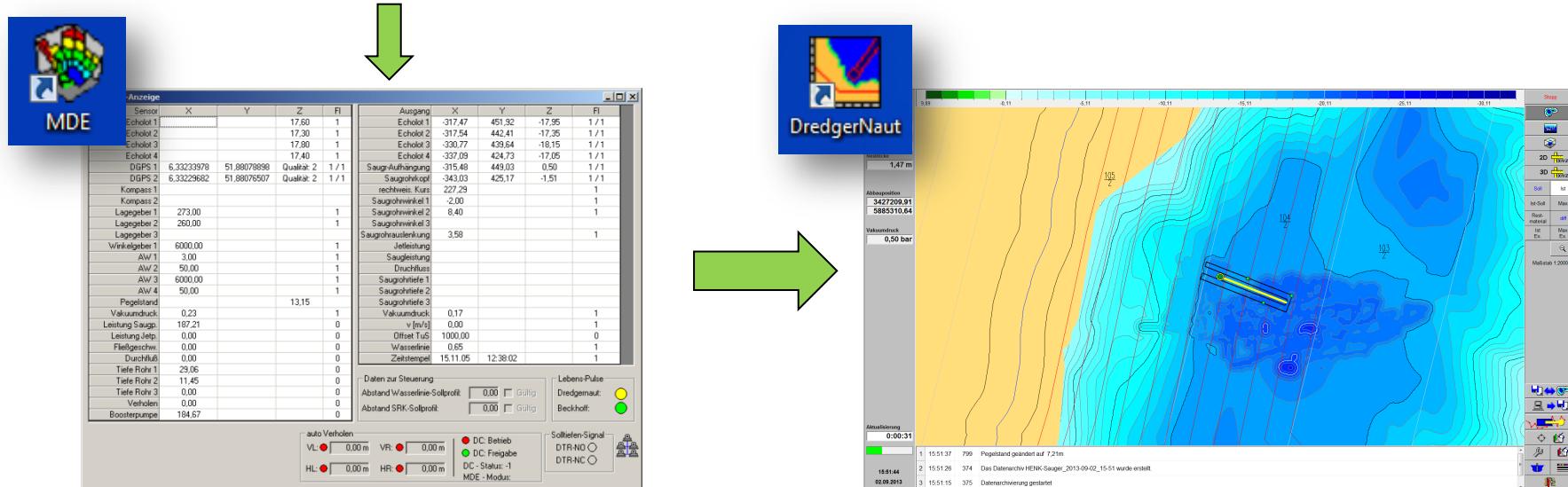
Exit

For detailed information consult the

DredgerNaut Manager manual.



3 Measuring data acquisition MDE



The measuring data acquisition program **MDE** (German: **Messdatenerfassung**) is the interface between the sensors and the visualization program **DredgerNaut**. The **MDE** continually reads the measuring data from the sensors (DGPS-receiver, echo sounders and inclinometers) and does the preprocessing. Additionally, the **MDE** acts as the interface between the control system of the excavation device and **DredgerNaut**.

When the measuring data acquisition program (MDE) is not running, the DredgerNaut system will not receive any sensor data and change to a FAULT-status.

The screenshot shows the DredgerNaut software interface. On the left, a table titled "Raw data" is displayed with various sensor readings. A green circle labeled "1" points to the "Echolot 4" row. On the right, another table titled "Local coordinates" shows sensor positions. A green circle labeled "2" points to the "Saugr.-Aufhängung" row. At the bottom, there are control buttons for "auto Verholen" and "Daten zur Steuerung".

	Y	Z	Fl
Echolot 1	17,60	1	
Echolot 4	17,30	1	
	17,80	1	
	17,40	1	
DGPS 1	6,33233978	51,88078898	Qualität: 2 1 / 1
DGPS 2	6,33229682	51,88076507	Qualität: 2 1 / 1
Kompass 1			
Kompass 2			
Lagegeber 1	273,00		1
Lagegeber 2	260,00		1
Lagegeber 3			
Winkelgeber 1	6000,00		1
AW 1	3,00		1
AW 2	50,00		1
AW 3	6000,00		1
AW 4	50,00		1
Pegelstand		13,15	
Vakuumdruck	0,23		1
Leistung Saugp.	187,21		0
Leistung Jetp.	0,00		0
Fließgeschw.	0,00		0
Durchfluß	0,00		0
Tiefe Rohr 1	29,06		0
Tiefe Rohr 2	11,45		0
Tiefe Rohr 3	0,00		0
Verholen	0,00		0
Boosterpumpe	184,67		0

Ausgang	X	Y	Z	Fl
Echolot 1	-317,47	451,92	-17,95	1 / 1
Echolot 2	-317,54	442,41	-17,35	1 / 1
Echolot 3	-330,77	439,64	-18,15	1 / 1
Echolot 4	-337,09	424,73	-17,05	1 / 1
Saugr.-Aufhängung	-315,48	449,03	0,50	1 / 1
Saugrohrkopf	-343,03	425,17	-1,51	1 / 1
rechtsweis. Kurs	227,29			1
Saugrohrwinkel 1	-2,00			1
Saugrohrwinkel 2	8,40			1
Saugrohrwinkel 3				
Saugrohrauslenkung	3,58			1
Jettleistung				
Saugleistung				
Druchfluss				
Saugrohrtiefe 1				
Saugrohrtiefe 2				
Saugrohrtiefe 3				
Vakuumdruck	0,17			1
v [m/s]	0,00			1
Offset TuS	1000,00			0
Wasserlinie	0,65			1
Zeitstempel	15.11.05	12:38:02		1

Daten zur Steuerung		Lebens-Pulse	
Abstand Wasserlinie-Sollprofil:	0,00	<input type="checkbox"/> Gültig	Dredgernaut:
Abstand SRK-Sollprofil:	0,00	<input type="checkbox"/> Gültig	Beckhoff:

auto Verholen		Solltiefen-Signal	
VL:	0,00 m	VR:	0,00 m
HL:	0,00 m	HR:	0,00 m
		DC: Betrieb	DC: Freigabe
		DC - Status: -1	DTR-NO
		MDE - Modus:	DTR-NC

Local coordinates

2

Meaning of the status indicators:

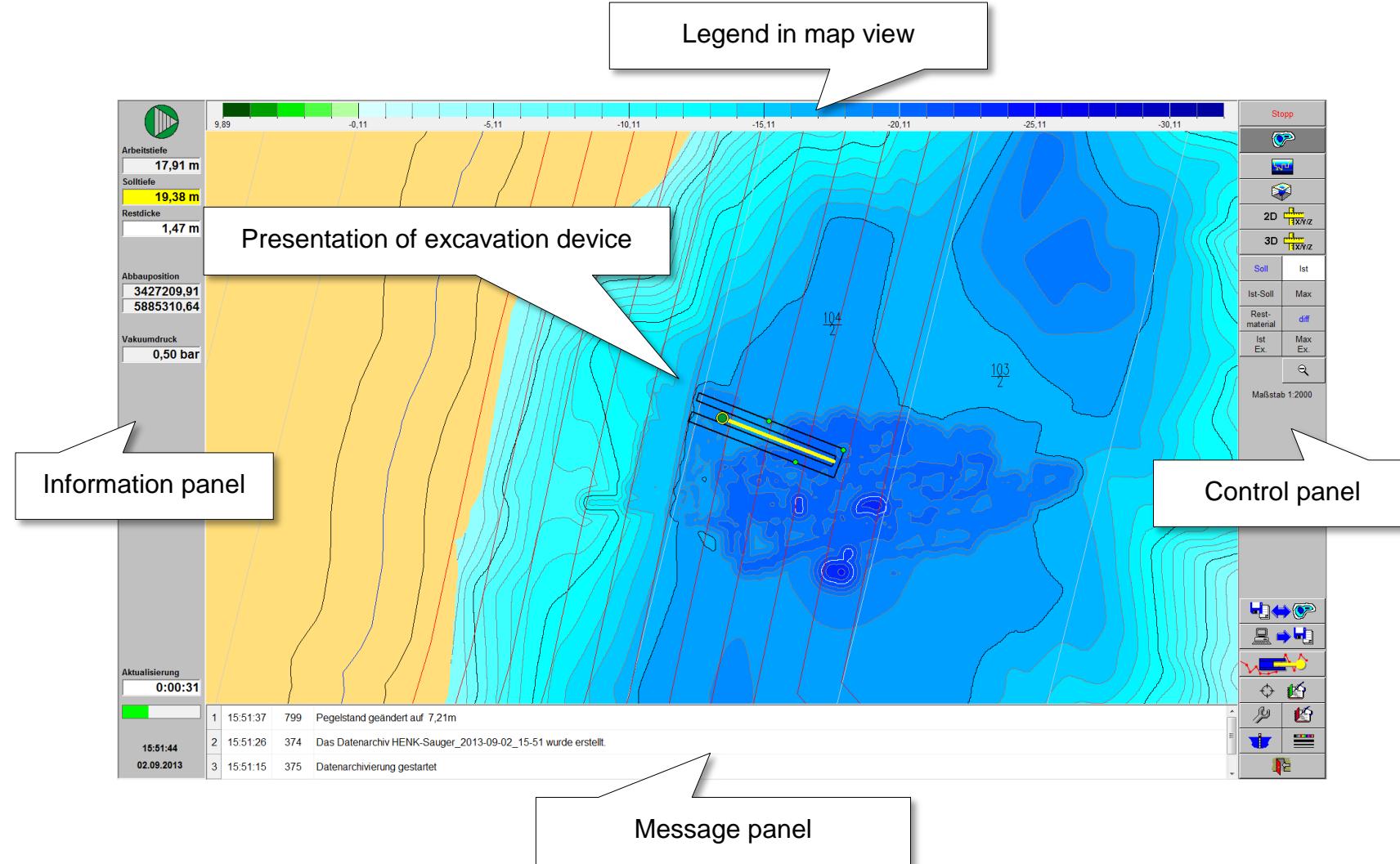
- 2: The sensor does not transmit any data/is off or not present
- 0: The sensor is transmitting data, but the values are not usable/plausible.
- 1: The sensor transmits correct values.

The DGPS-receiverer shows a two-part status indicator:

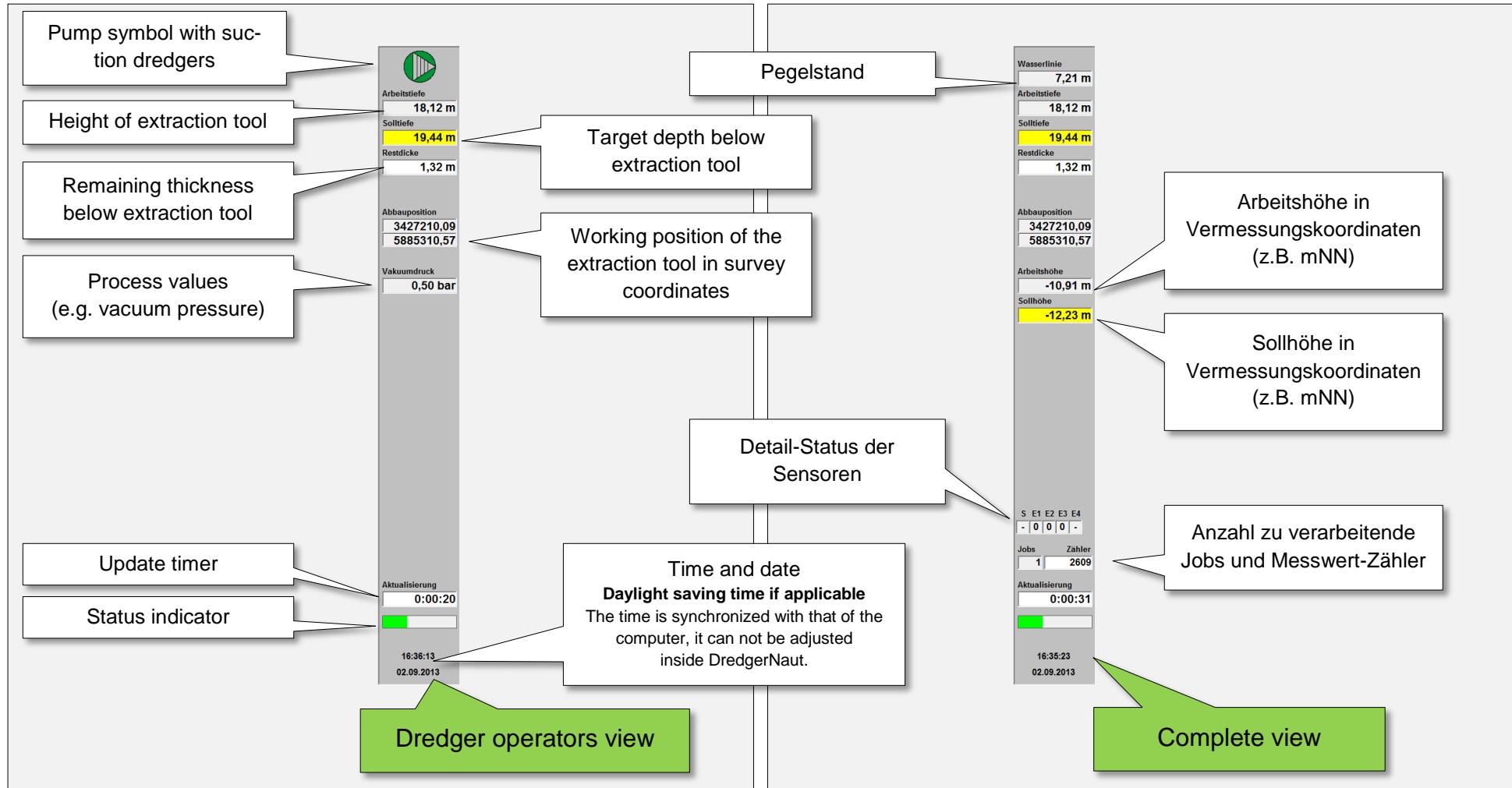
- 2/-2: No reception or the sensor is off or not present.
- 3/0: Correctional signal is not received.
- 4/0: Data-set is corrupted.
- 1/1: GPS- and correctional signal okay.

The configuration of the measuring data acquisition program differs from system to system and type of excavation device (suction dredger, bucket chain- or grab dredger).

4 Graphical user interface

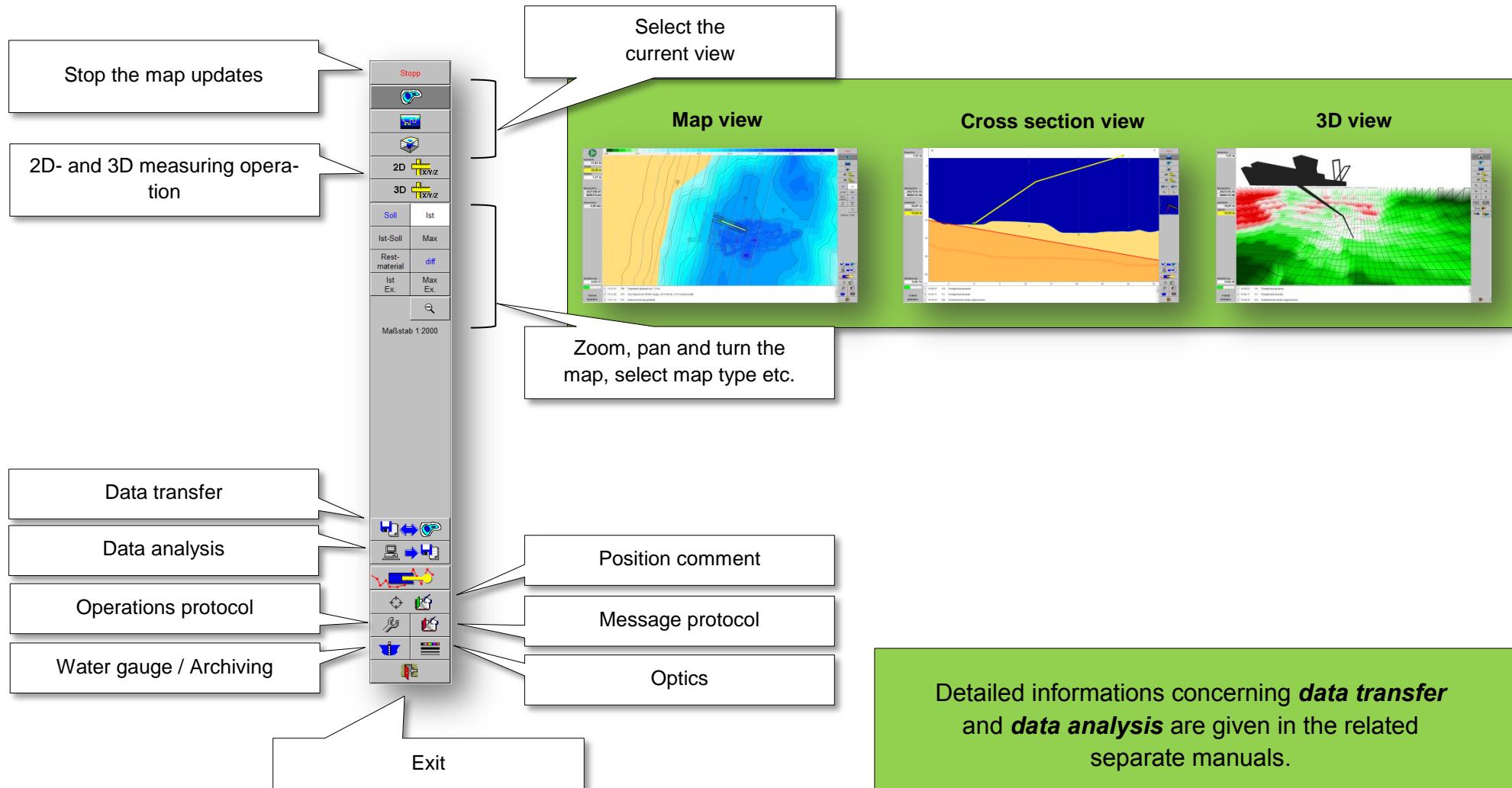


4.1 Information panel



The information panel has got several configurations.

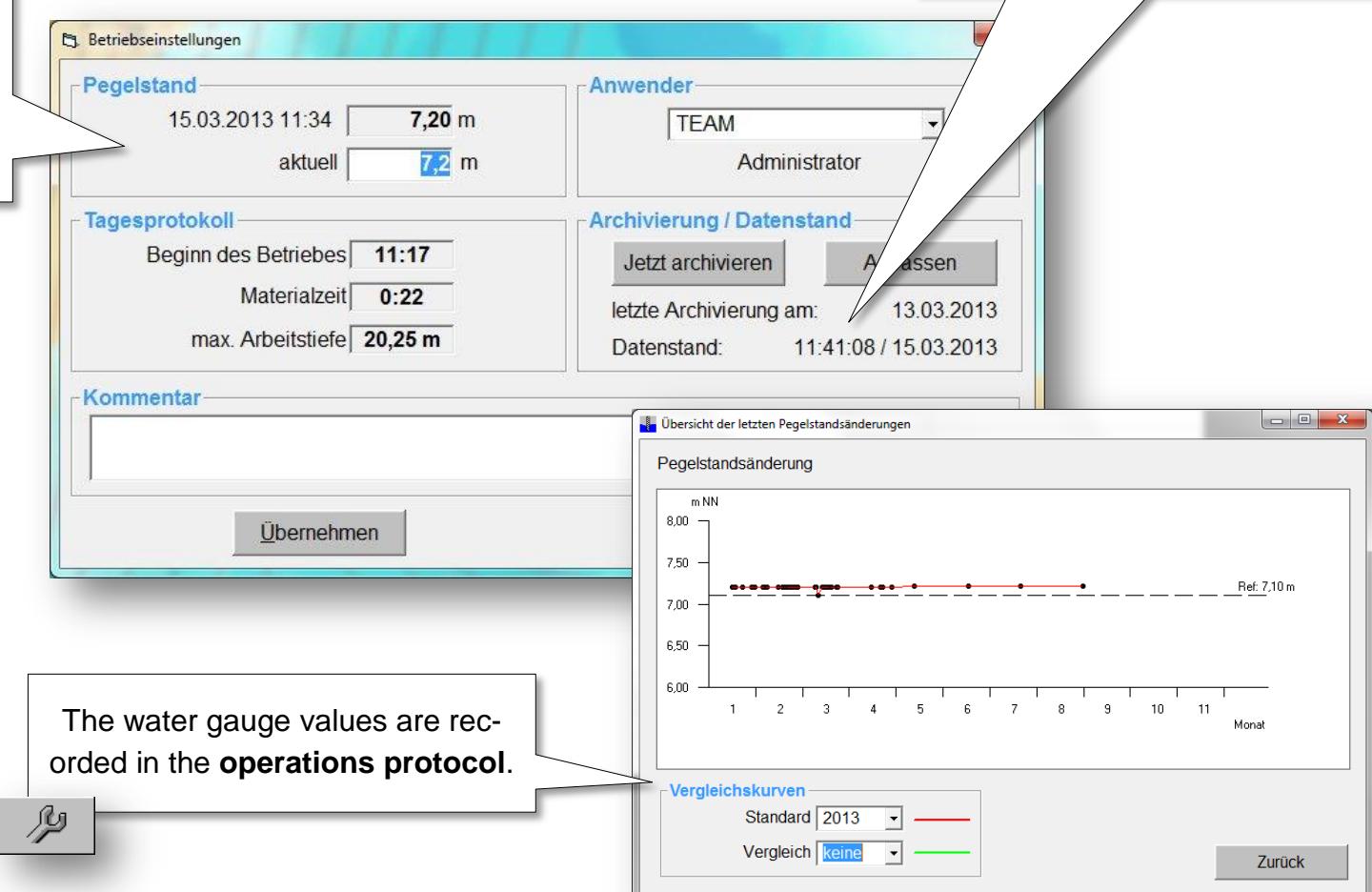
4.2 Menu structure



5 Start of program

5.1 Setting the actual water gauge

During the start of program setting the actual water gauge value will be requested in regular intervals. Depending on the frequency of fluctuations this may be necessary up to daily.

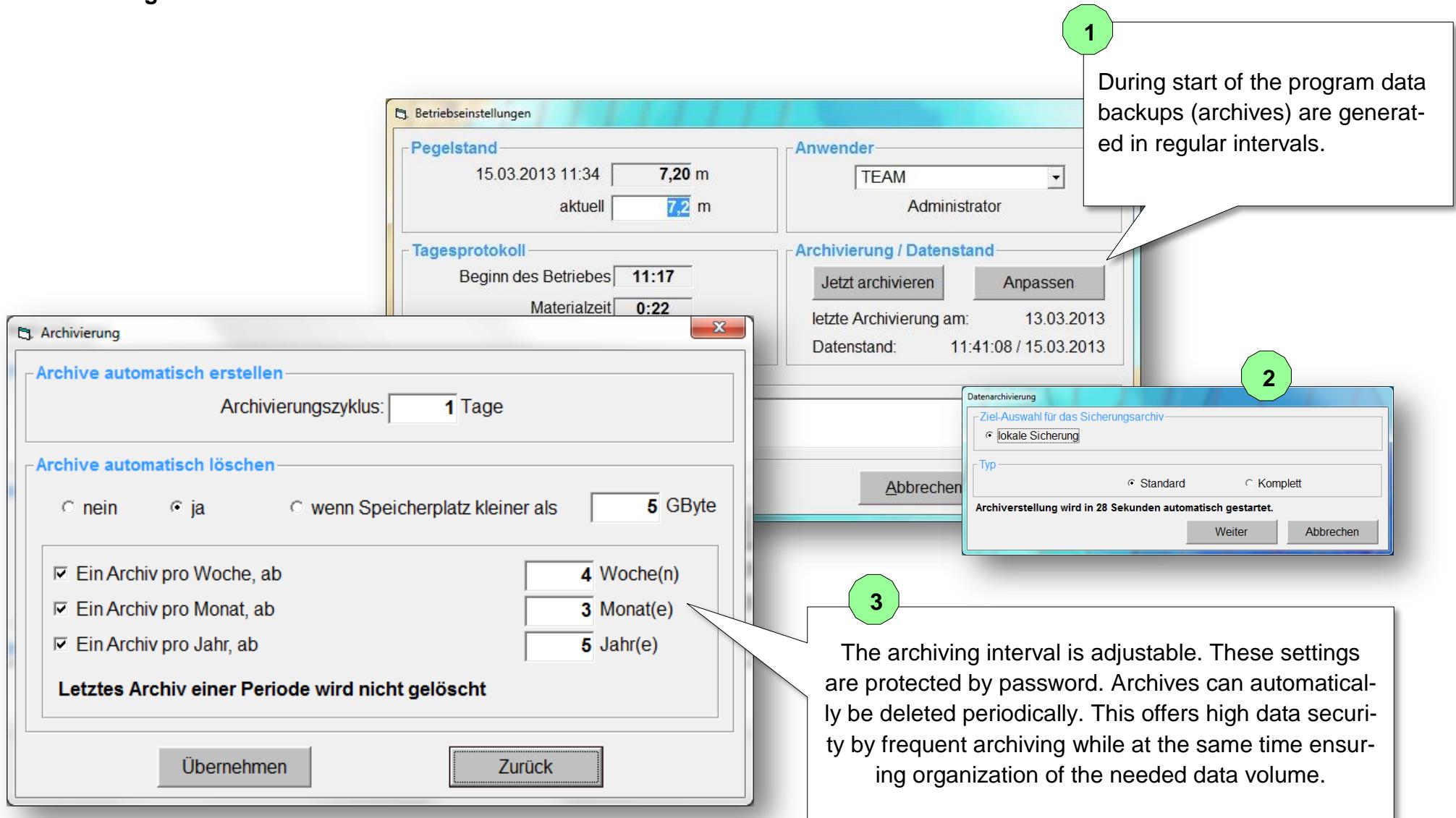


Daylight saving time, if applicable
The time is synchronized with that of the computer, it can not be adjusted inside DredgerNaut.

The water gauge values are recorded in the **operations protocol**.

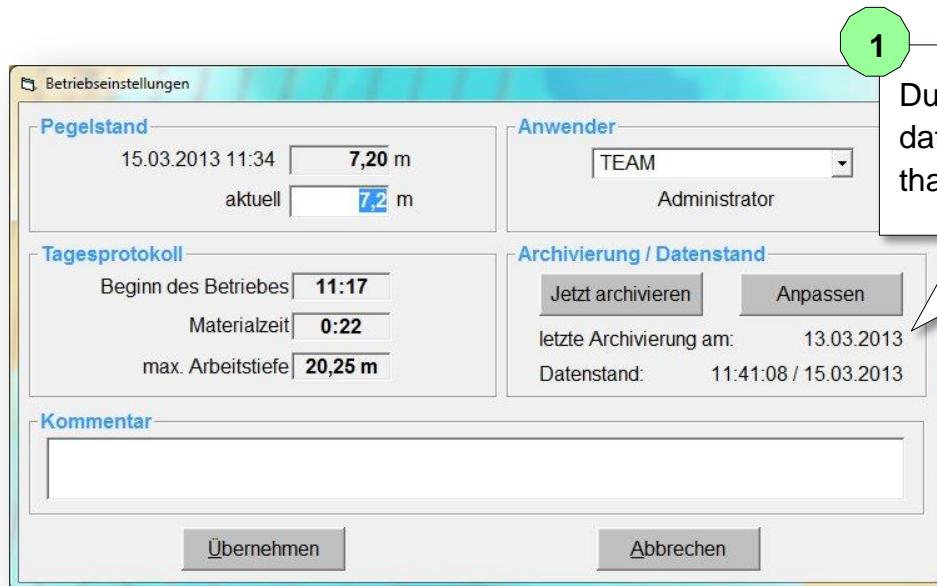


5.2 Archiving

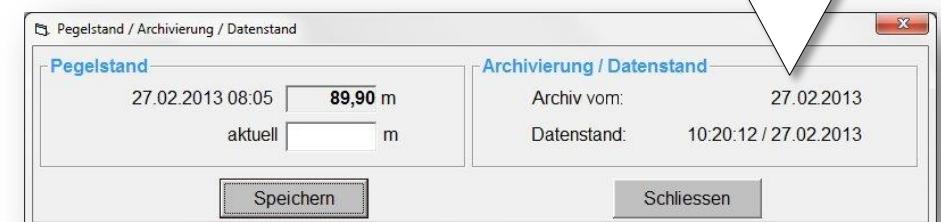


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During **online operation** the data status will usually be *newer* than the last archive.



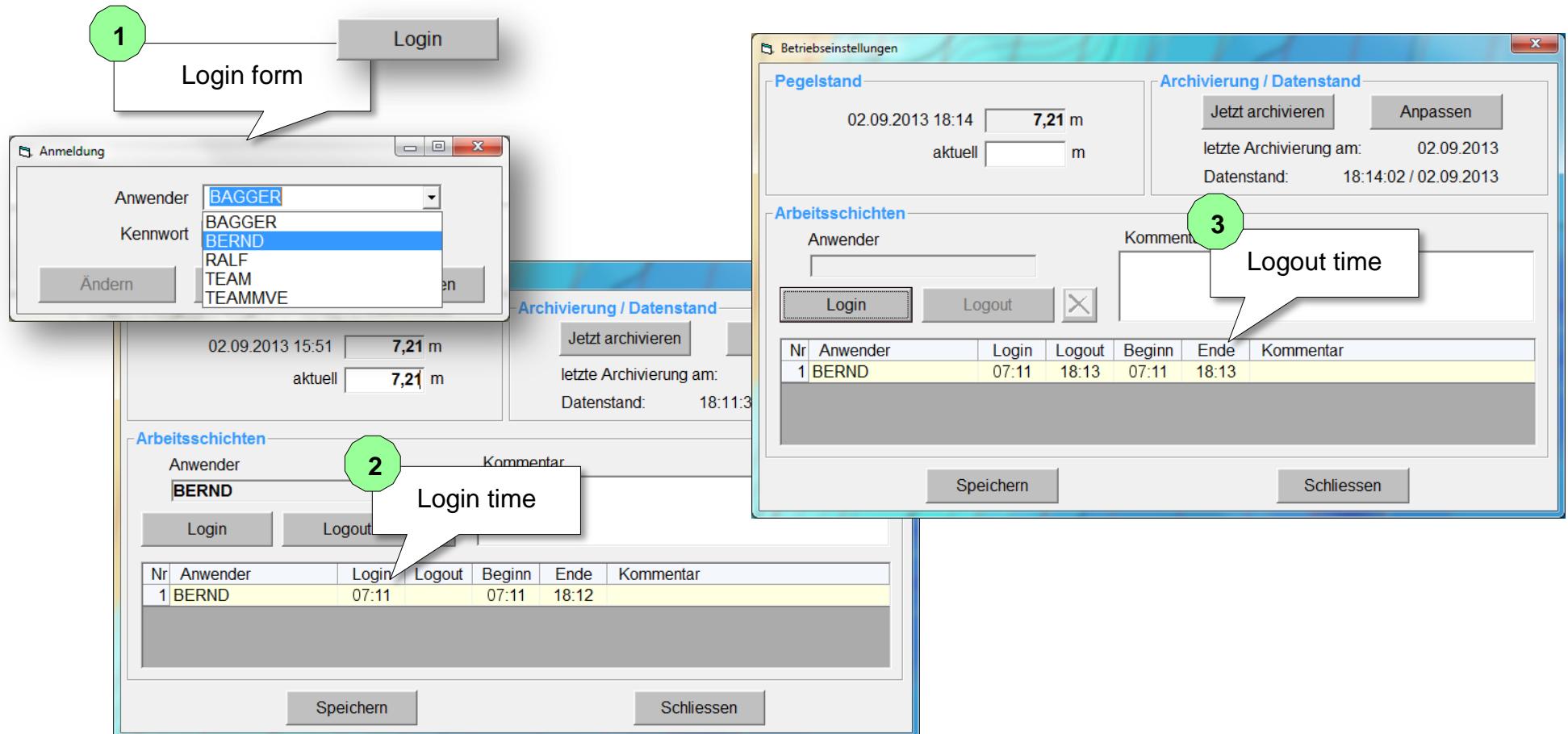
During **offline operation** the date of the archive and the date of the data status will usually be the *same (basis data)*. The date of the archive is the date it was created on the online system



When creating an archive from a **data-copy** during **offline-operation** the date of the archive will not be changed (using the **DredgerNaut Manager**). The date of the archive is the date of the creation on the online system (excavation device). If the data status of the copy is altered (e.g. by deleting existing or importing new data) the date of the data status will then be newer than the date of the archive.

5.3 Login

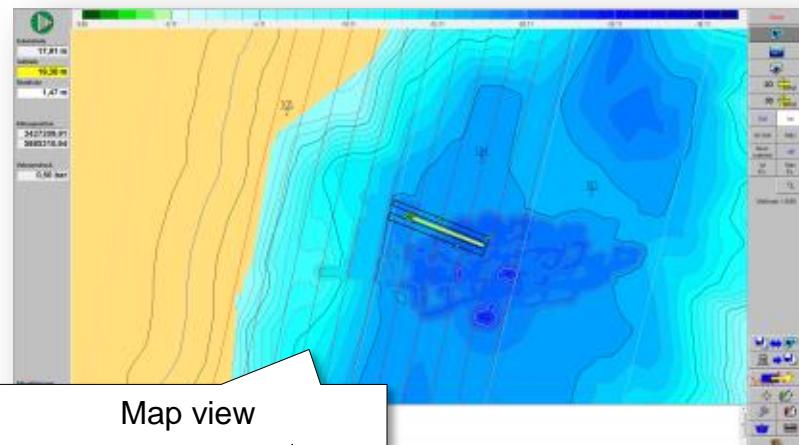
If the operations protocol is used employee related, the employees have to login at the start of their shift and logout again at the end.



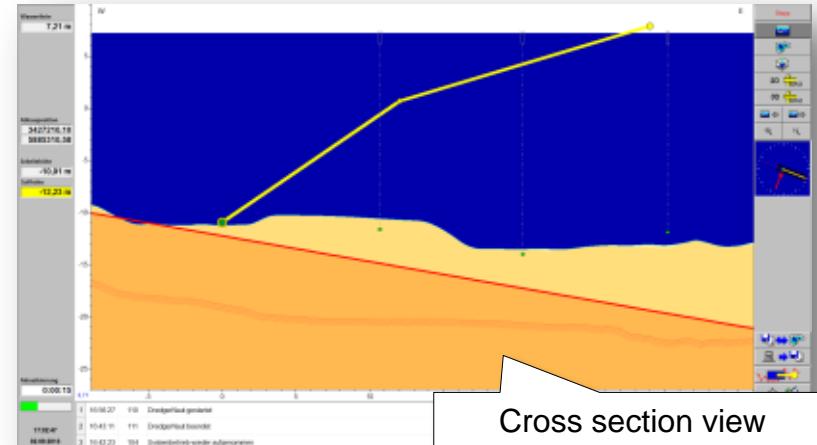
6 Excavation operation

During excavation operation the excavation device can be presented in one of three views, **map view**, **cross section view** or **3D view**.

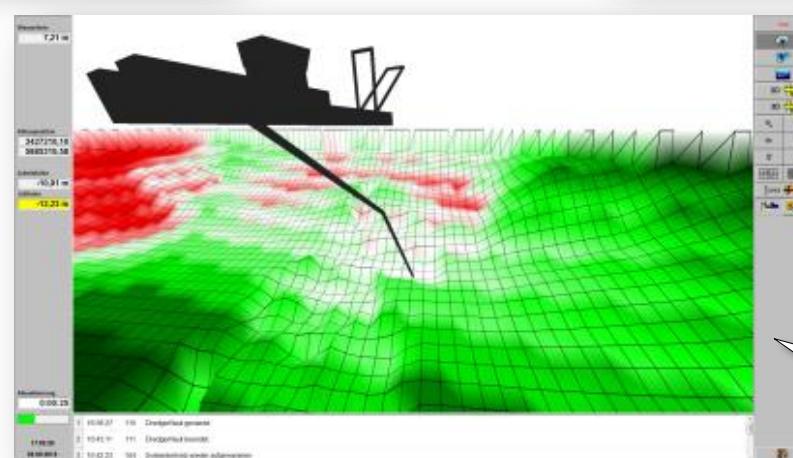
The 3D view is only available with suction dredgers.



Map view



Cross section view



3D view

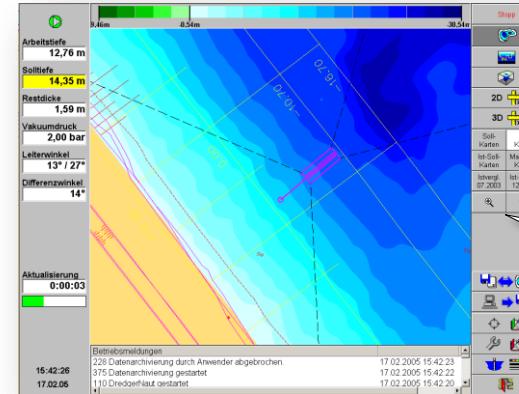
Introduction

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6.1 Map types

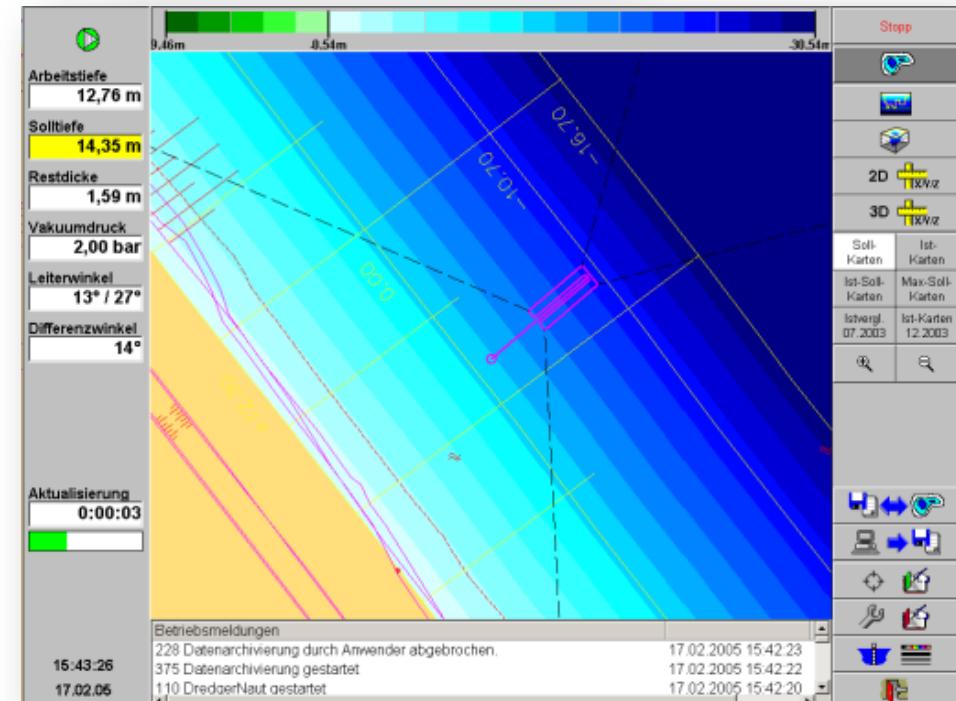
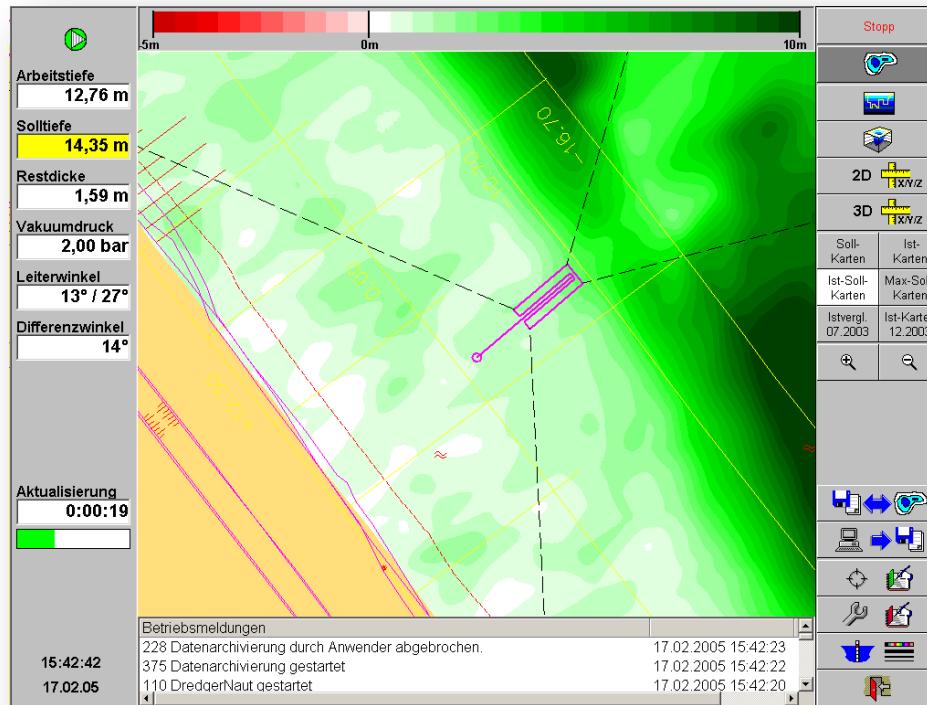
By default the following map types are available:

- *Target profile*
- *Actual profile*
- *Difference profile(s)*
- *Max. depth map(s)*



Switch
map type

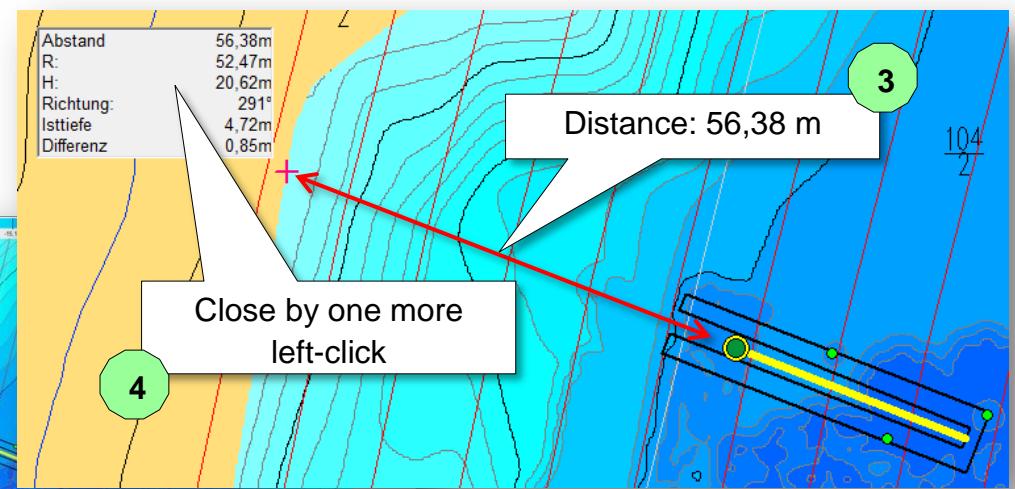
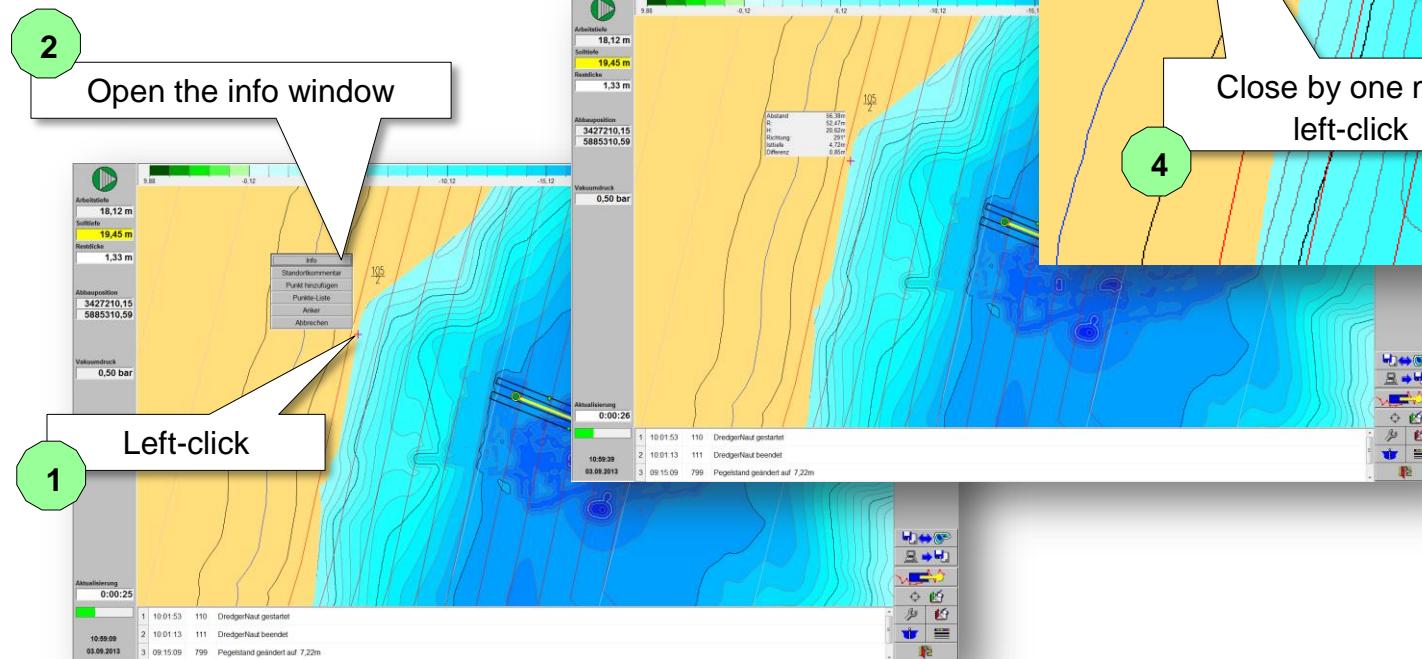
Zoom in (larger)
or out (smaller)



6.1.1 Info window

By a left-click onto the map a pulldown menu appears. Clicking on 'info' shows a window containing information for the clicked position and the distance from there to the extraction tool. Close the info window by clicking into it.

Clicking onto another position of the map while the info window is still open will move the window over there and show informations for the new position

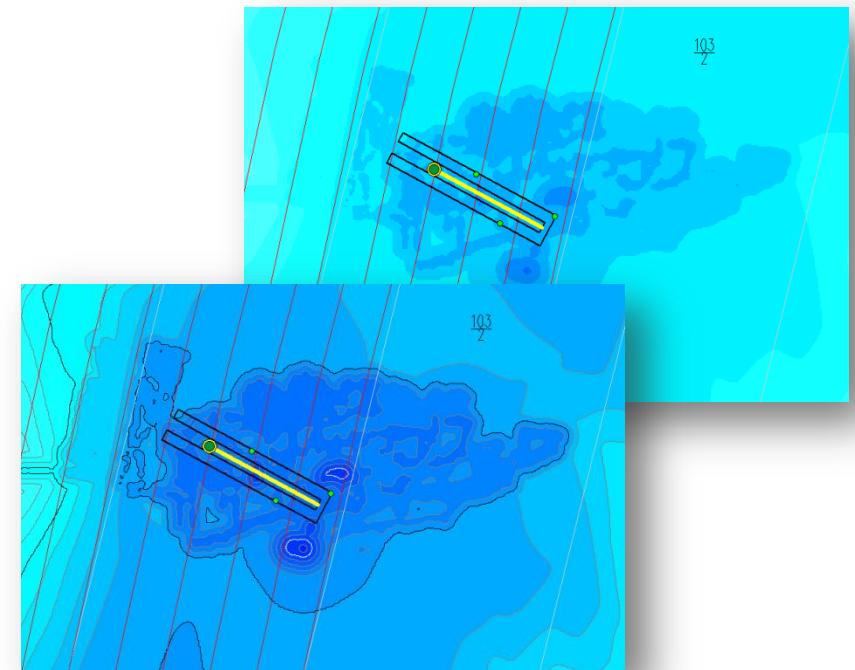
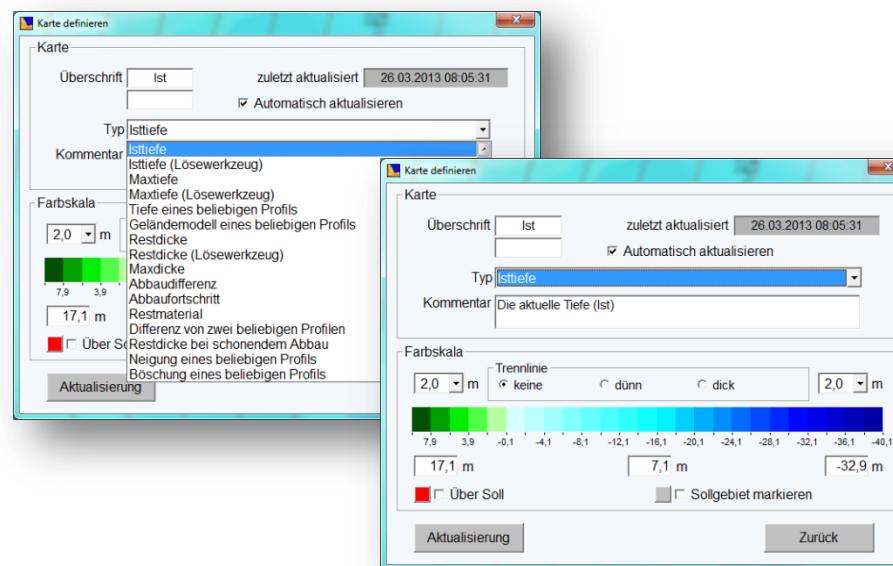


6.1.2 Map type configuration

Double-clicking a map type button will show the configuration window for that map. The colour scale, depth gradient and separating lines for the map can be defined here. The contrast can be increased here and the resolution enlarged.

Besides the default map types (Target-, Actual-, Difference- and Max-profile) additional map types can be defined.

- *Depth of the extraction tool (Actual- and Max.-depth as well as remaining thickness) independent from the echo sounders*
- *Excavation progress*
- *Inclination (in degrees) or slope-profiles (in 1 by x)*
- *...and much more.*



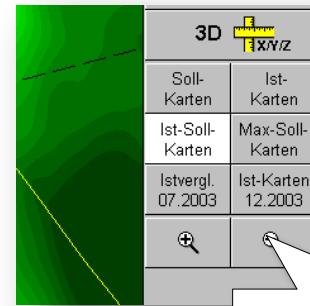
Introduction

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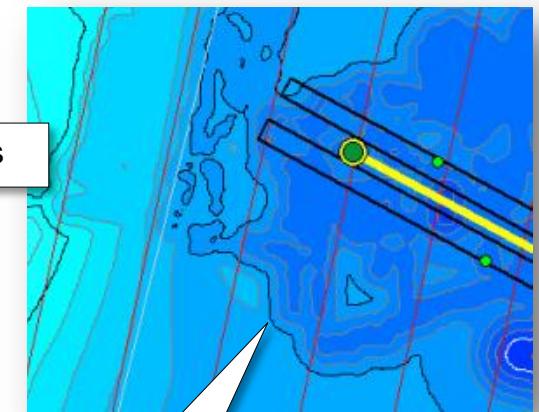
The scope of four buttons for the default map types

- *Target-profile*,
- *Actual-profile*,
- *Actual-Target- and*
- *Max-Target-profile*

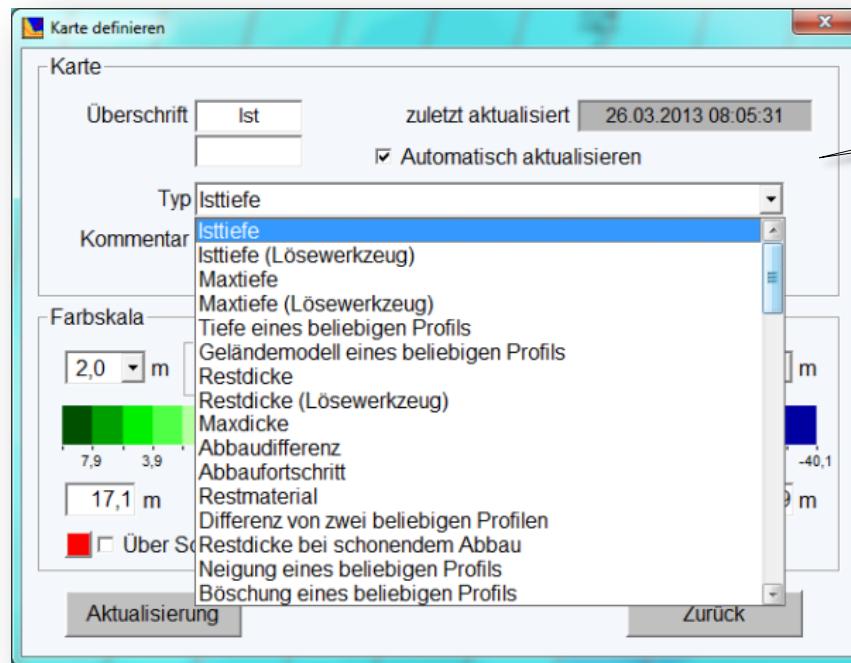
can be extended by additional buttons.



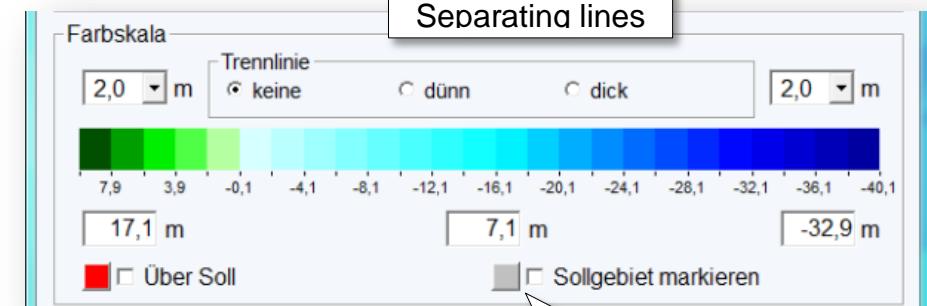
Additional map types



Separating lines



After selecting the new map type the colour scale will be defined.

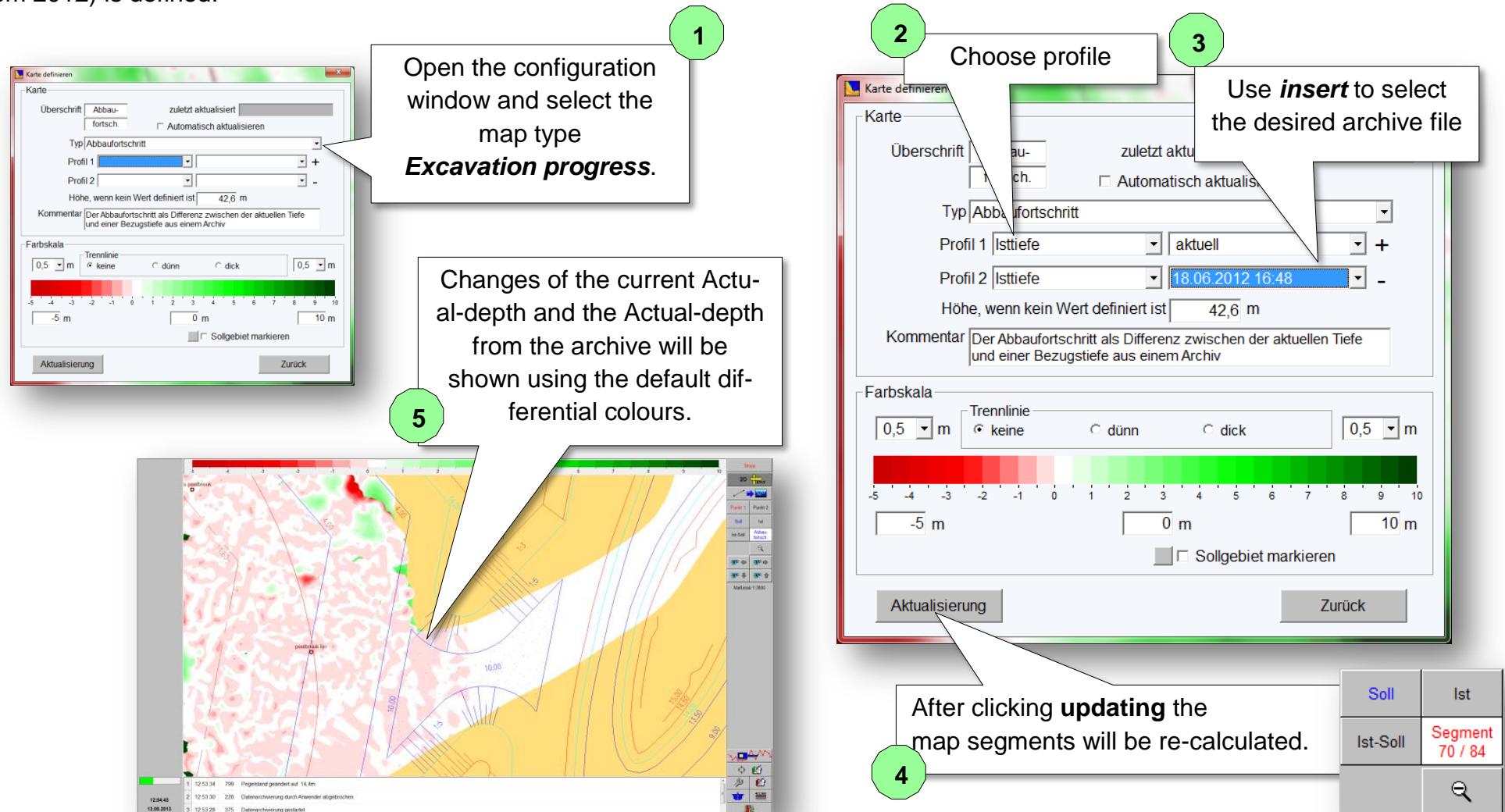


In each map the target area can be marked by its own colour.

Map type	Colour scale	Description
Actual depth		The current depth (Actual)
Actual depth (extraction tool)		The current depth (Actual) of the extraction tool (echo sounder values not considered)
Maximum depth		The maximum depth reached until now (Max)
Maximum depth (extraction tool)		The maximum depth reached until now by the extraction tool (Max) without depiction of dislocated material
Depth of an arbitrary profile		Depth of an arbitrary profile (including Archive-profiles from available data backups)
Terrain model of a (random) profile		Digital terrain model of any profile
Remaining thickness		The difference between the current and the allowed depths (Actual - Target)
Remaining thickness (extraction tool)		The difference between the current and the allowed depths (Actual – Target) of the extraction tool without depiction of dislocated material
Maximum thickness		The difference between the maximum and the allowed depths (Max - Target)
Excavation difference		The difference between the current depth and the depth max. 15 minutes ago
Excavation progress		The excavation progress depicted as the difference between the current depth and a related reference depth from an archive
Remaining material		The thickness of the available excavation material (where the current depth is known identical to the remaining thickness Actual - Target)
Difference of two arbitrary profiles		The Difference of two arbitrary profiles (including Archive-profiles from available data backups)
Remaining thickness with sensible mining		Remaining thickness with sensible mining
Inclination of an arbitrary profile		Inclination of an arbitrary profile in degrees. A horizontal surface has an inclination equal to zero degrees.
Slope of an arbitrary profile		Slope of an arbitrary profile depicted as relation of depth difference by distance.
Thickness to the start of a layer		Thickness to the start of the layer x (Actual – Layer x)
Thickness of a layer to the target depth		Thickness of the layer x to the allowed depth
Thickness of a layer		Thickness of the layer x

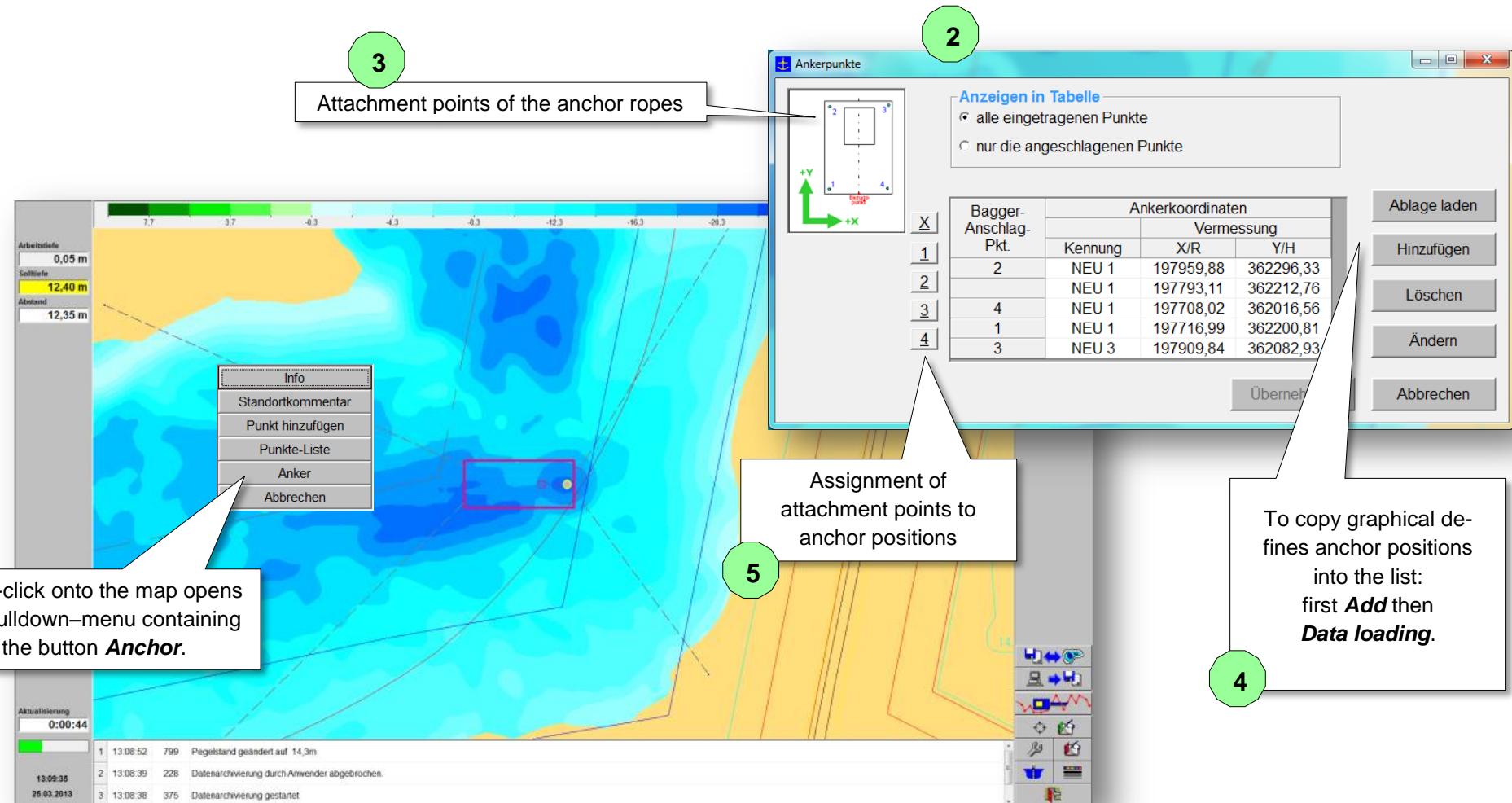
Example

Creation of a map type **Excavation progress**. A difference profile between the current Actual-depth and the Actual-depth out of an archive (from 2012) is defined.



6.1.3 Depiction of the anchor positions

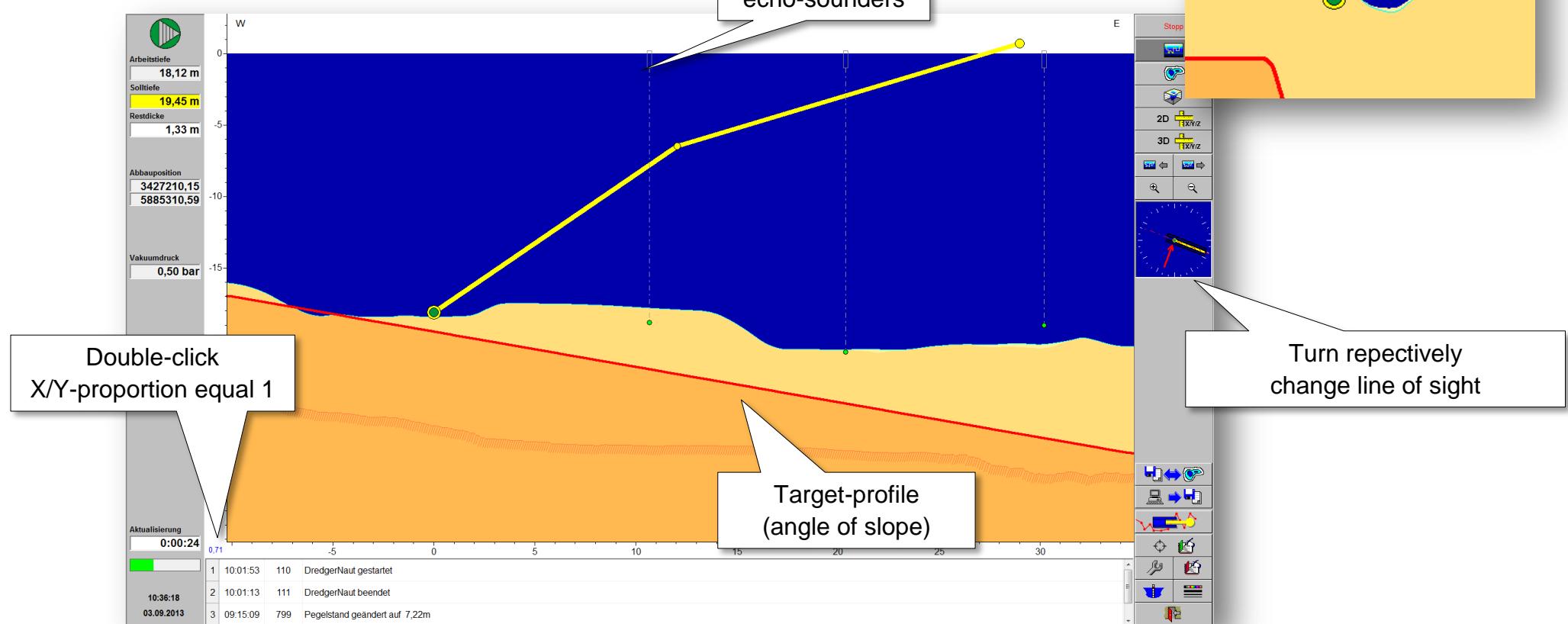
The anchor positions will be defined graphical or as coordinate-sets. Using the depiction of the anchor ropes the possible mobility of the excavation device can be estimated.



6.2 Cross section view

The extraction tool is depicted in the cross section view. The following movement options are available:

- Zoom in (larger) and out (smaller)
- Pan
- Turn (changing the line of sight)

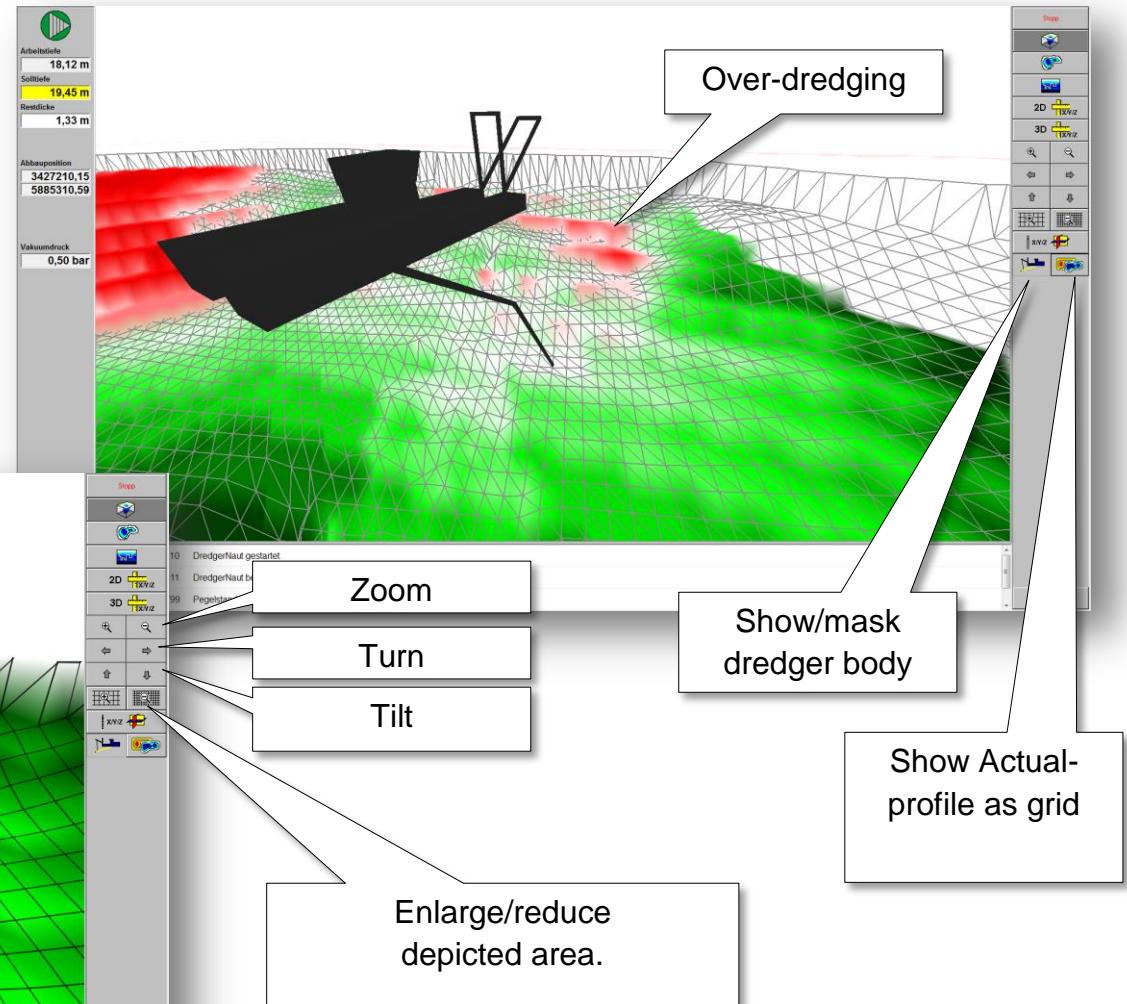
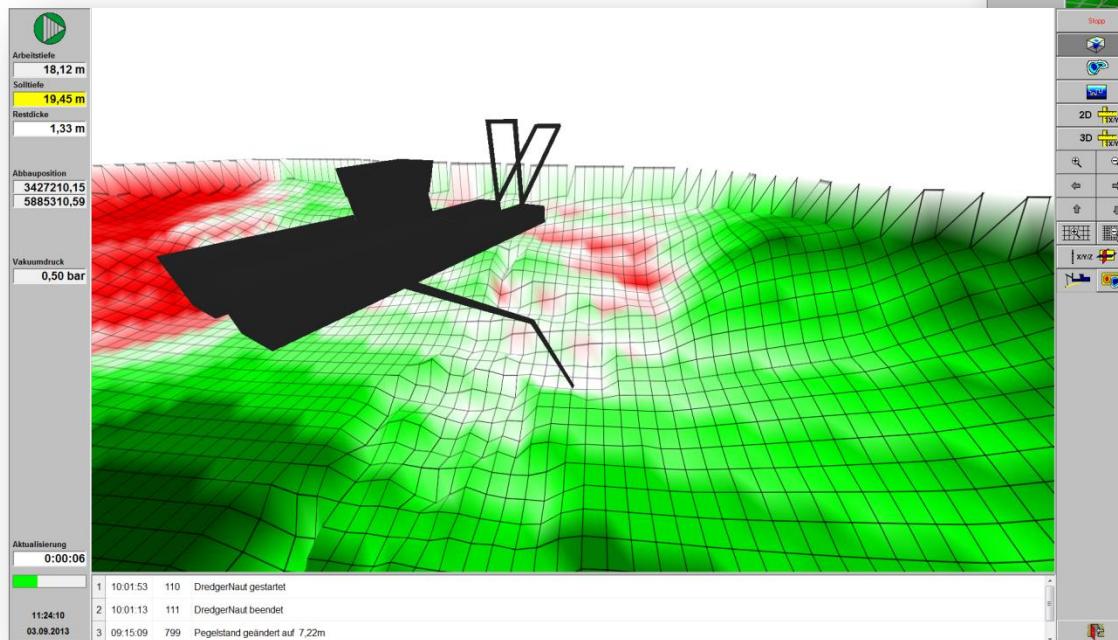


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6.3 3D view

In 3D view the excavation device is shown three-dimensional. The pontoons (dredger body) can be masked so that only the extraction tool remains visible. The depicted areas can be enlarged respectively reduced. The Actual-profile will be shown either as a grid or a surface. If the Actual-profile is drawn as a grid the Target-profile will be shown as a surface. If the Target-profile surface penetrates the Actual-depths grid this visualizes over-dredging.

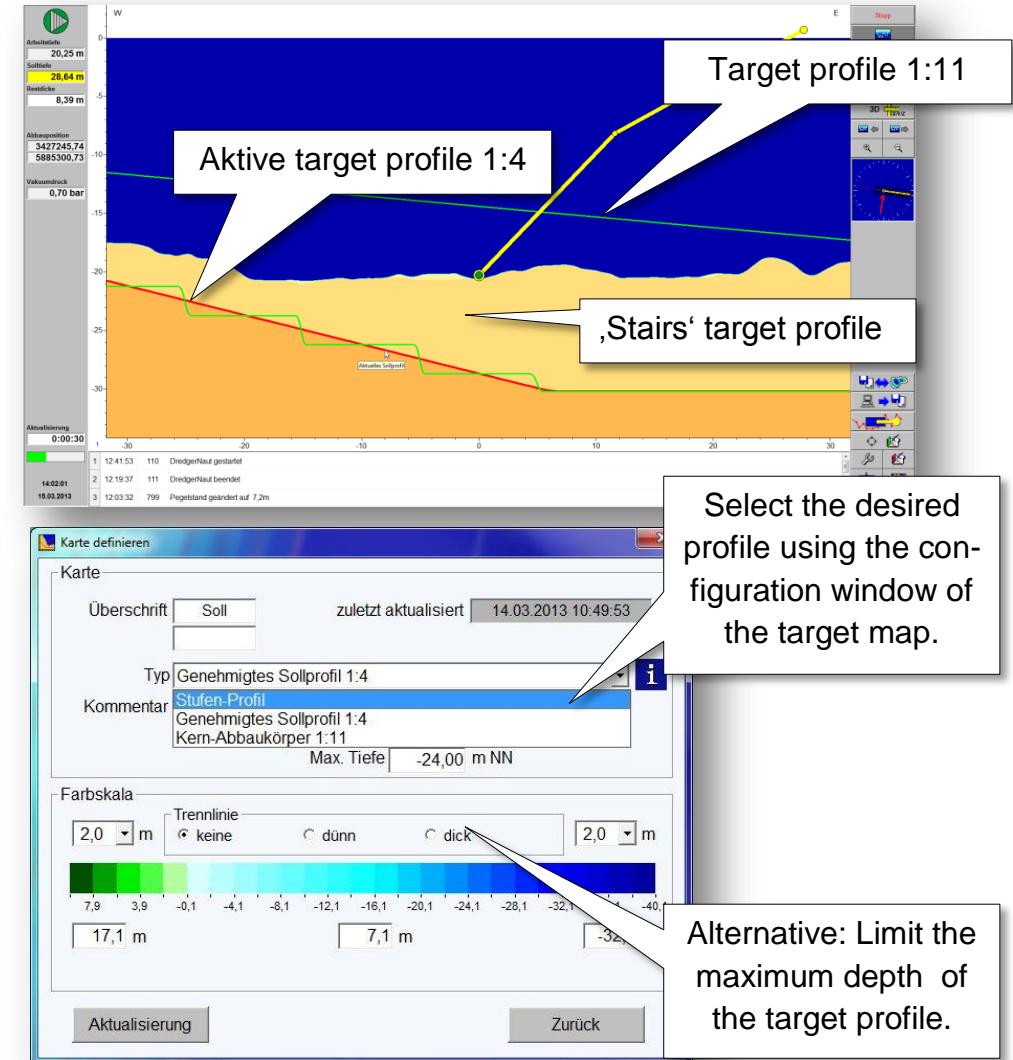
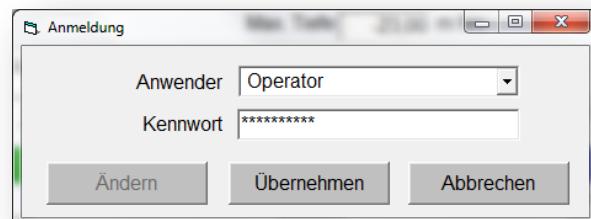


7 Target profile

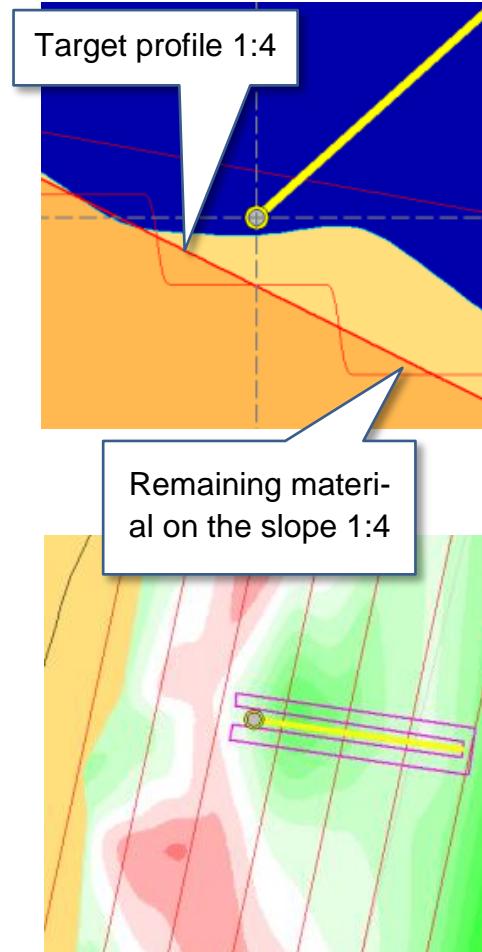
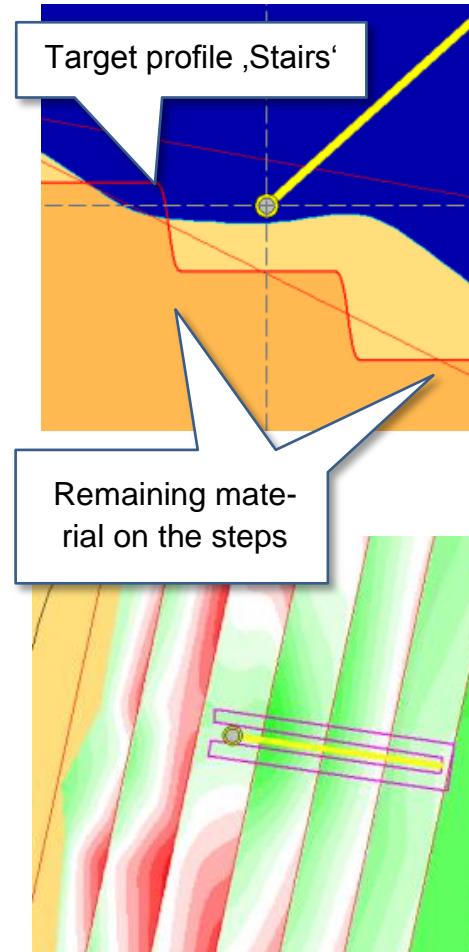
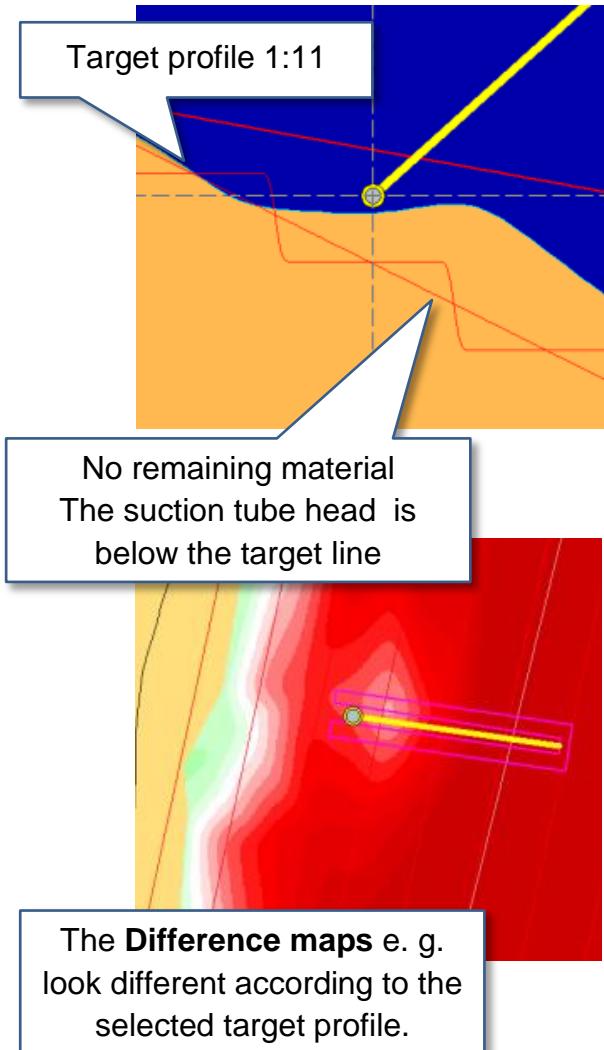
The target profile will be defined e.g. by the landscape architect or the survey office. Additional helper- or working-target profiles can be used to accompany or support the excavation during different phases.

DredgerNaut offers the following functions to administer target profiles:

- It is possible to switch between different target profiles.
- The maximum depth can additionally be limited independent from the target profile.
- After switching to another target profile, dependant maps will be recalculated
 - Target map, difference maps, etc..
- Depiction of existing target profiles in cross section view using differentiated colours including tool-tips.
- Switching target profiles is protected by password.



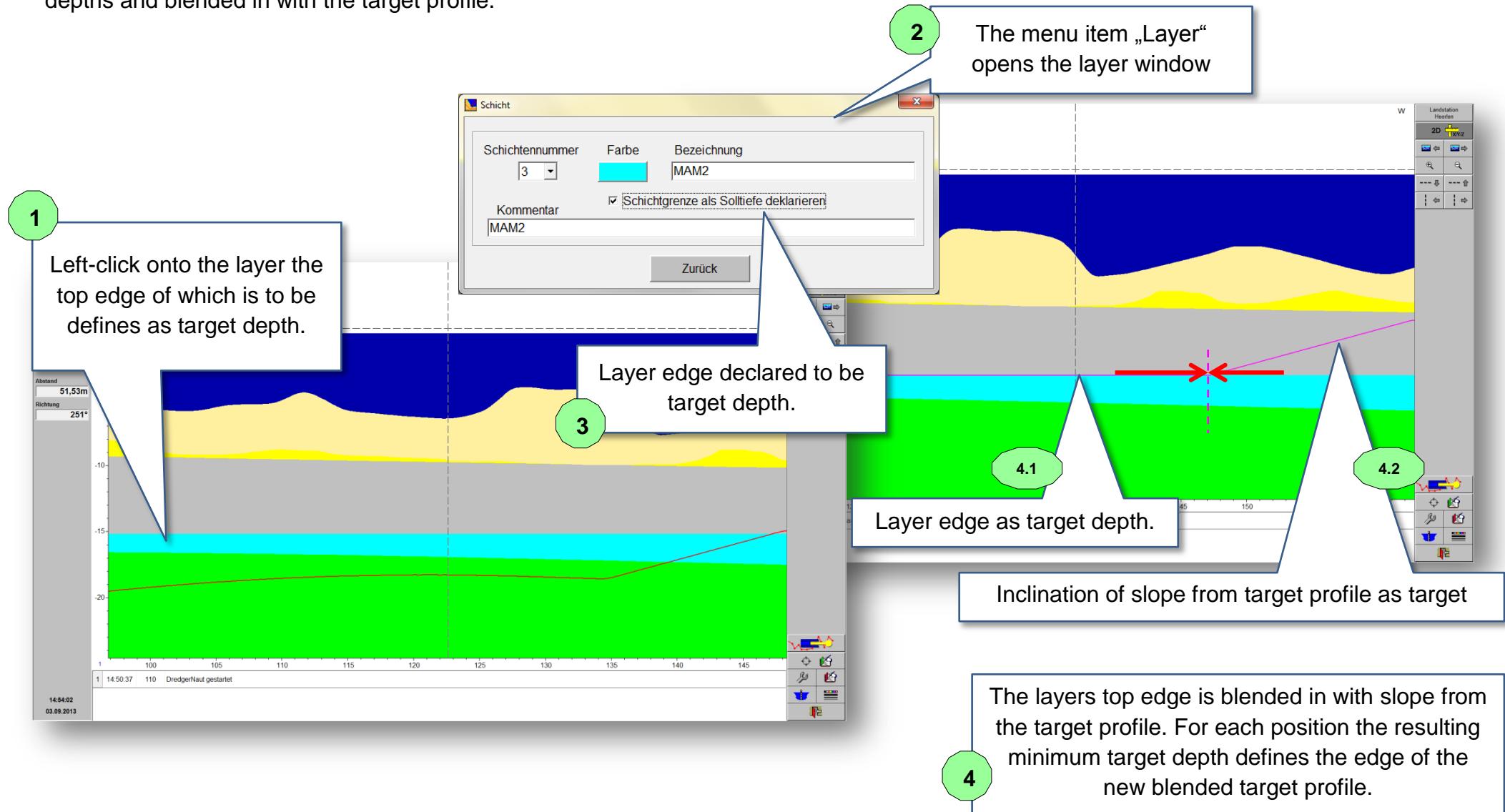
After selecting the desired target profile the dependant maps (Target-, difference-, Max-maps, etc.) will be re-calculated.



Introduction

DredgerNaut

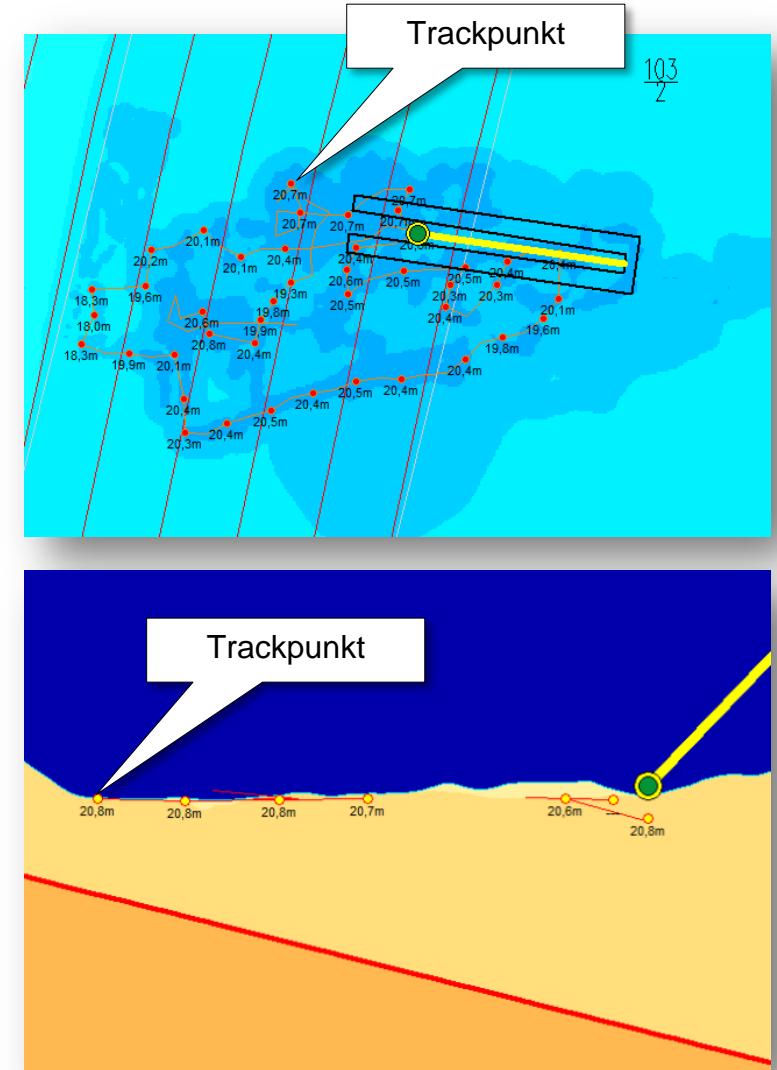
Drilling and layer analysis data can be incorporated into the 3D terrain profiles. The top edges of layers can be defined to act as maximum depths and blended in with the target profile.



8 Track data

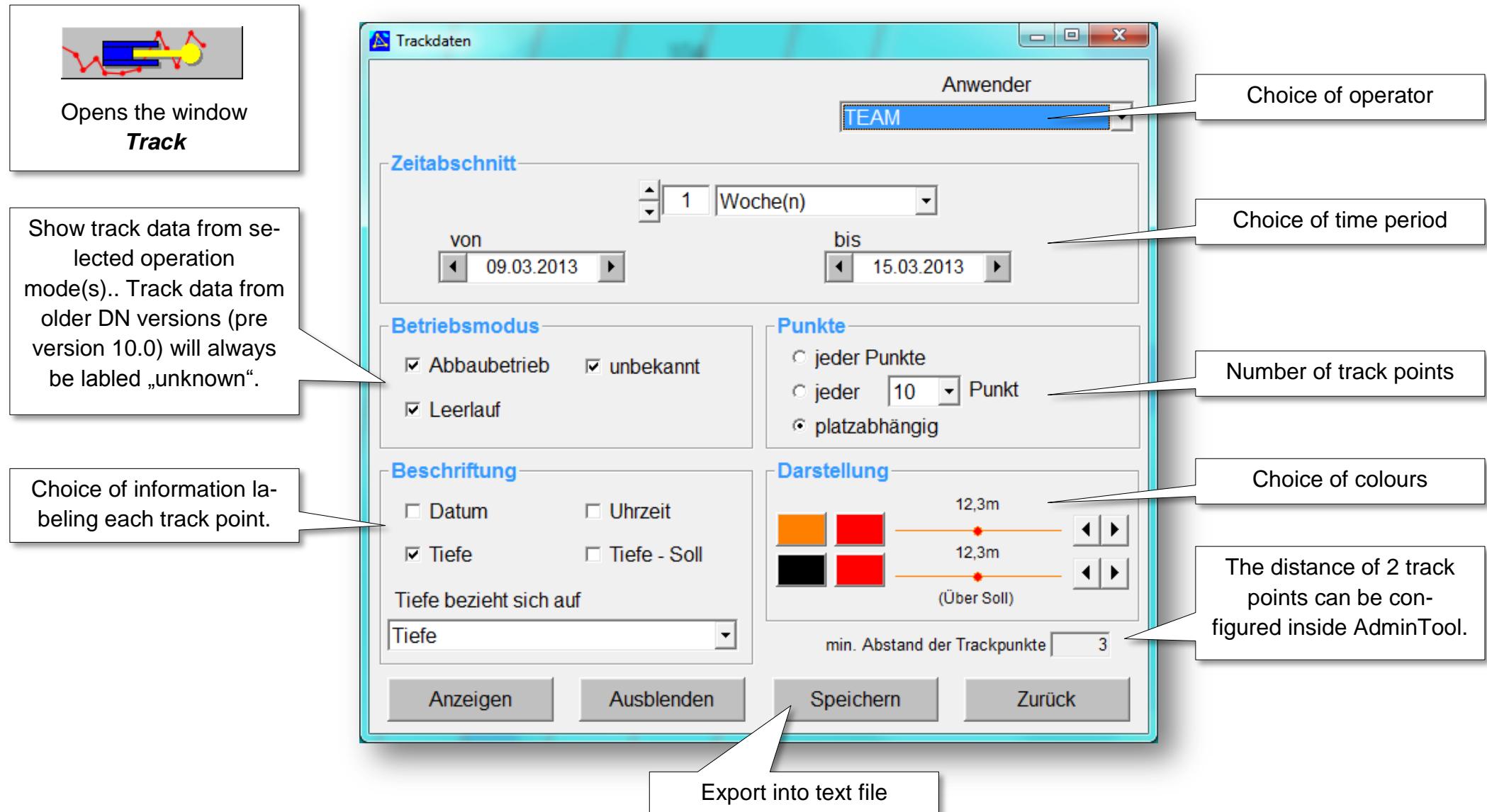
The track data show the positions of the excavation device over time in map and cross section view. Thus, the excavation process becomes comprehensible and transparent. The following function options exist:

- *Presentation of the track-trail in online and measuring mode.*
- *Presentation of the track-trail in map and cross section view*
- *Labeling a track point with*
 - *Current-depth, max-depth or depth of extraction tool,*
 - *Date and*
 - *time*
- *The track-trail is differentiable between excavation operation and idle.*
- *The track-trail is differentiable between operators (e.g. employees).*
- *The track-trail is differentiable between different excavation devices at the same mining location.*
- *The track-trail display colours are selectable (text, lines und points).*
- *The track-trail can be viewed in detail in tables.*
- *The track-trail can be exported into a text file.*



Introduction

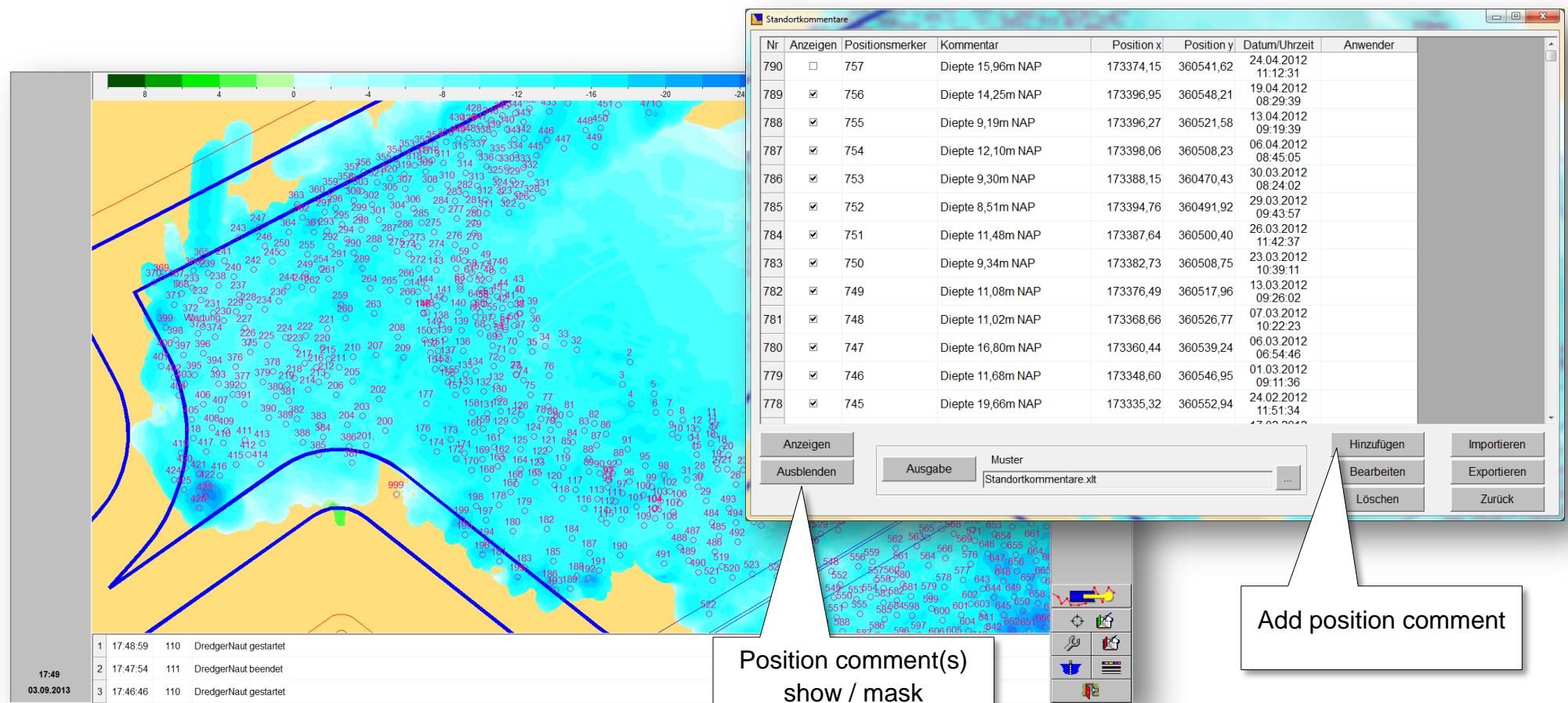
DredgerNaut



9 Position comments, drilling data and layers

9.1 Position comments

The current excavation position can be saved as a position comment and later be shown in the map for orientation. Text comments (like clay, wood, good quality, etc.) further document the excavation.



9.2 Drilling data and layers

Individuell drillings can be depicted as position comments including the results of the analysis. The integration of the analysis results has to be done offline.

The screenshot displays the DredgerNaut software interface, which includes a map view, a detailed drilling log, a cross-section viewer, and a comment viewer.

Map View: Shows a coastal area with various drilling locations marked as points. A callout box labeled "Drilling" points to one of these points. Another callout box states: "A position comment can be opened by clicking it in the map."

Drilling Log: A table titled "Standortkommentare" listing drilling positions and their details. A callout box states: "The list of position comments contains also drillings."

Nr.	Anzeigen	Positionsmerker	Kommentar	Position x	Position y	Datum/Uhrzeit	Anwender
32	<input checked="" type="checkbox"/>	SCHÖPPF	Schopfadr	4372982,73	5543693,37	03.2012 14:04	TEAM
31	<input checked="" type="checkbox"/>	BL7	205,85/1,8/6,2	4373155,48	5543500,89	03.2012 14:04	TEAM
30	<input checked="" type="checkbox"/>	BL6	205,55/3,5	4373263,00	5543473,66	03.2012 14:04	TEAM
29	<input checked="" type="checkbox"/>	BL5	205,77/2,8/5	4373239,24	5543490,96	03.2012 14:04	TEAM
28	<input checked="" type="checkbox"/>	BL4	206,08/2,5/5	4373212,47	5543509,42	03.2012 14:04	TEAM
27	<input checked="" type="checkbox"/>	BL3	206,13/2,4	4373189,17	5543521,65	03.2012 14:04	TEAM
26	<input checked="" type="checkbox"/>	BL2	206,05/2,6	4373169,00	5543531,34	03.2012 14:04	TEAM
25	<input checked="" type="checkbox"/>	BL1	206,06/2,3/5	4373184,70	5543540,89	03.2012 14:04	TEAM
24	<input checked="" type="checkbox"/>	RK55	205,74/3,4	4373177,75	5543541,69	03.2012 14:04	TEAM
23	<input checked="" type="checkbox"/>	RK54	205,73/3,2/5	4373278,50	5543640,88	03.2012 14:04	TEAM
22	<input checked="" type="checkbox"/>	RK53	205,93/7,2/7	4373269,98	5543674,98	03.2012 14:04	TEAM
21	<input checked="" type="checkbox"/>	RK52	206,01/2,5/4,3	4373249,11	5543698,19	03.2012 14:04	TEAM
20	<input checked="" type="checkbox"/>	RKS1	205,93/3,4/2,4	4373230,15	5543681,46	03.2012 14:04	TEAM
19	<input checked="" type="checkbox"/>	BOHR19	205,84/5,1/2,5,4	4373182,50	5543433,66	03.2012 14:04	TEAM
18	<input checked="" type="checkbox"/>	BOHR18	205,54/8,2/7,3,3	4373251,50	5543556,75	03.2012 14:04	TEAM
17	<input checked="" type="checkbox"/>	BOHR17	205,58/8,3/2,8	4373288,77	5543611,22	03.2012 14:04	TEAM
16	<input checked="" type="checkbox"/>	BOHR16	205,90/1,1/1,5	4373052,55	5543765,00	03.2012 14:04	TEAM
15	<input checked="" type="checkbox"/>	BOHR15	206,18/2,0/2,6,8	4373047,49	5543767,47	03.2012 14:04	TEAM
14	<input checked="" type="checkbox"/>	BOHR14	206,17/1,7/6,9	4373029,25	5543768,47	03.2012 14:04	TEAM
13	<input checked="" type="checkbox"/>	BOHR13	206,14/0,9/5,9	4372945,28	5543533,68	03.2012 14:04	TEAM
12	<input checked="" type="checkbox"/>	BOHR12	206,35/6,5/6	4372850,28	5543375,97	03.2012 14:04	TEAM
11	<input checked="" type="checkbox"/>	BOHR11	206,10/9,1/6,4,2	4372941,11	5543380,90	03.2012 14:04	TEAM

Cross-Section View: Shows a vertical profile of the seabed with various layers and analysis results. A callout box states: "Drilling positions will additionally be shown in cross section view."

Comment Viewer: A dialog box showing a position comment for "BOHR4". It includes fields for "Abstand" (40,33 m), "Nr" (4), "Positionsmerker" (BOHR4), and "Kommentar" (205,403/0,5/4,3). A callout box states: "Analysis results for drillings will be shown in cross section view."

10 Operations protocol

10.1 Default operations protocol

The operations protocol is intended to document production data and is available as Excel- or RTF-export.

Material time and time of operation

Tag	Wochentag	Beginn	Ende	Materialzeit	Betriebszeit	Pegel	X:	Y:	Tiefe	Anwender	Kommentar
1	Donnerstag	07:21	21:36	12:09	14:16	89,81	196671	324518	79,04	ADMIN	
2	Mittwoch	07:18	21:38	11:39	14:20	89,81	196697	324584	79,54	ADMIN	
3	Donnerstag	07:28	21:39	11:58	14:00	89,81	196718	324570	79,86	ADMIN	
4	Freitag	07:18	21:55	11:46	14:13	89,81	196651	324585	79,63	ADMIN	
5	Samstag										
6	Sonntag										
7	Montag	06:15	20:34	12:26	14:19		196725	324575	80,57		
8	Dienstag	06:11	21:01	10:34	12:51	89,81	196734	324582	80,79	ADMIN	
9	Mittwoch	06:22	20:40	13:22	14:18	89,79	196742	324599	81,48	ADMIN	
10	Donnerstag	12:25	23:59	6:48	7:22	89,71	196730	324612	81,63	ADMIN	
11	Freitag	06:15	23:59	13:01	14:29	89,71	196710	324611	81,38	ADMIN	
12	Samstag					196710	324606	88,72			
13	Sonntag					196710	324605	88,72			

Working time

Maximum depth

Operator

Logging water gauge

Choice of month

Excel-export

Water gauge history

10.2 Working time- and production data-acquisition

The operations protocol can be recorded differentiating by employee/operator and that way be used as working time and production data record, implementing password protection if needed.

Documentation of important production data

Employee

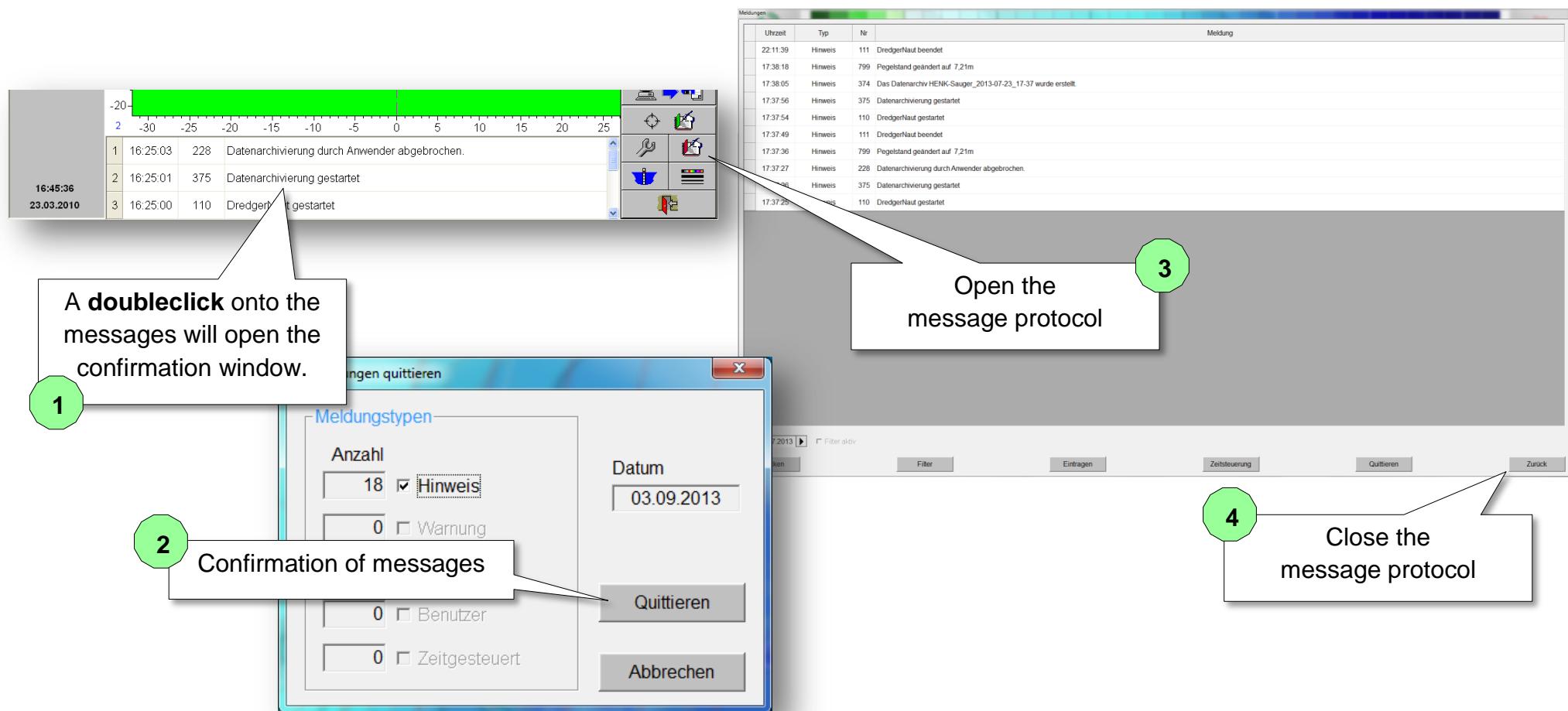
Working time

Choice of month

Excel-export

11 Message protocol

DredgerNaut will generate different messages during different situations (notes, warnings, etc.). The message protocol records the actions in the **DredgerNaut** system and facilitates error diagnostics.

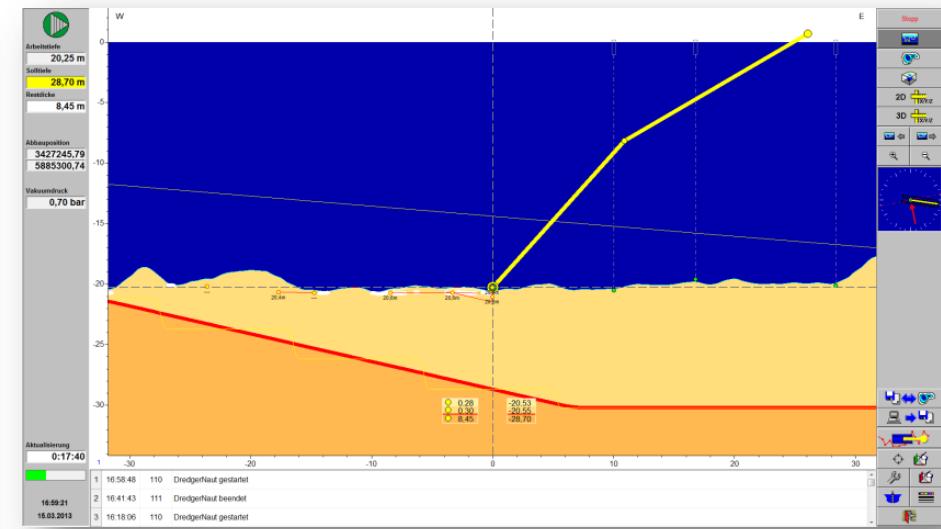
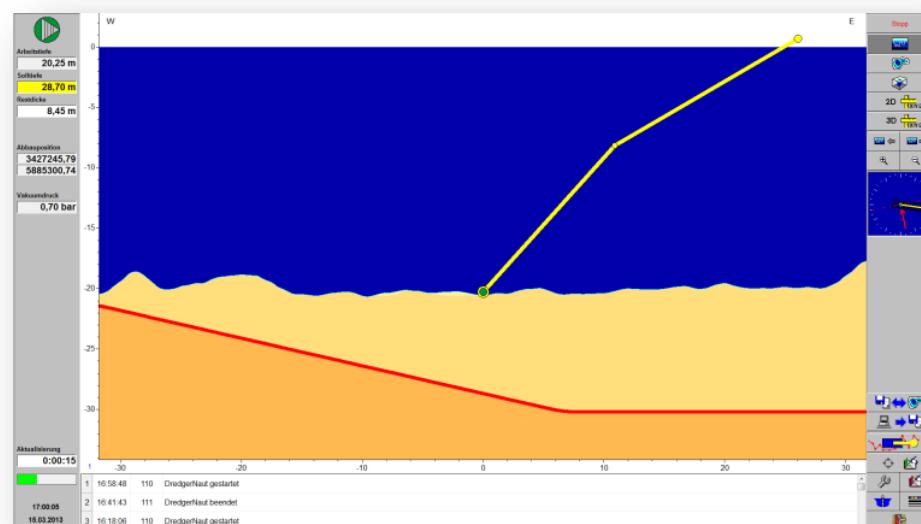
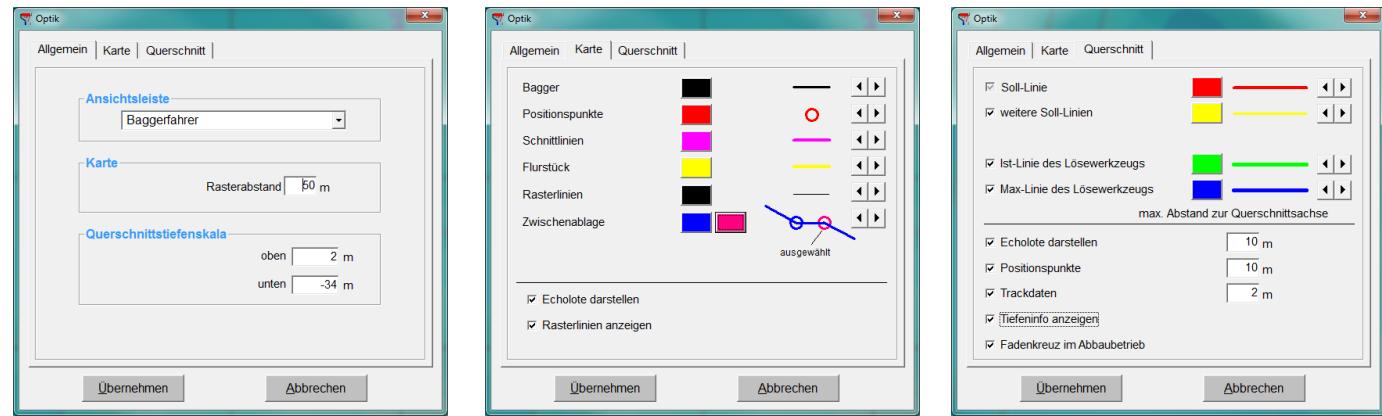


12 Visual appearance

The optical representation can be adjusted separately for **map** and **cross section view**.

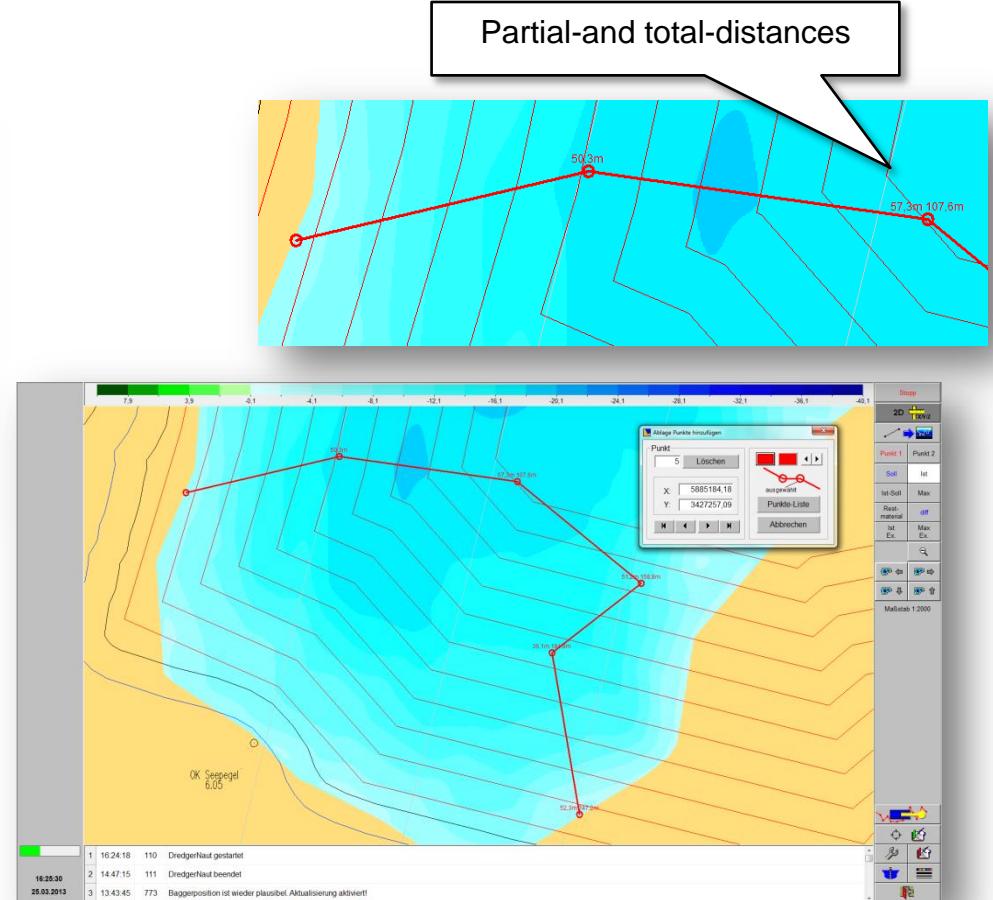
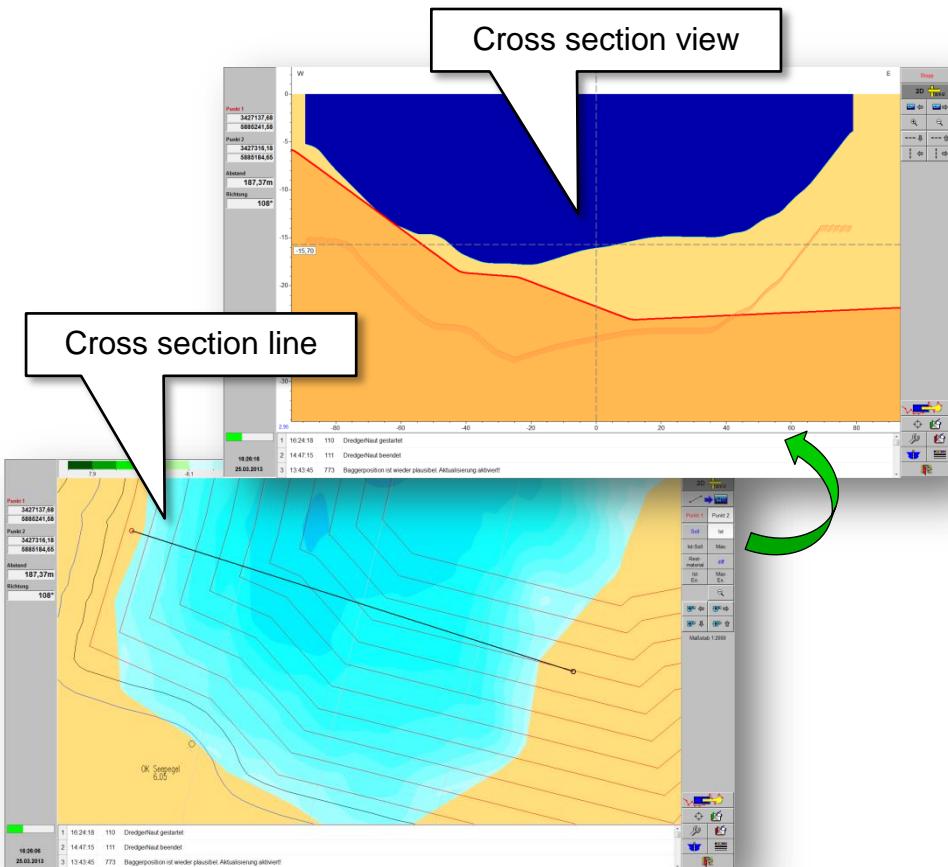
Optical settings:

- *additional target profiles*
- *depth of excavation tool*
- *echo sounders*
- *track data*
- *depth informations*
- *crosshairs*
- *raster lines*
- *etc.*



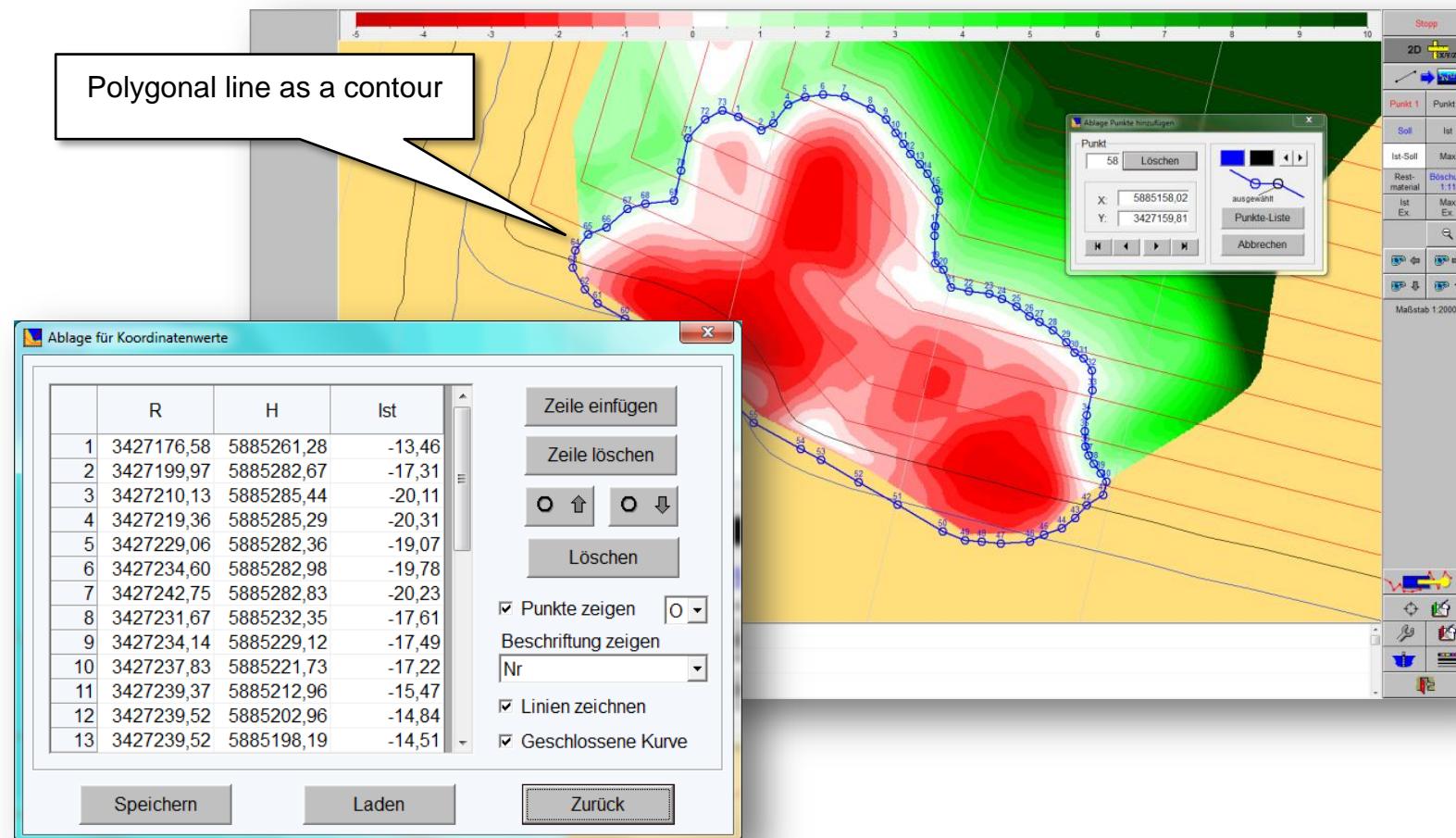
13 Measuring mode

Independent of the position of the excavation device freely configurable cross sections and measurements in the 3D terrain models are possible.



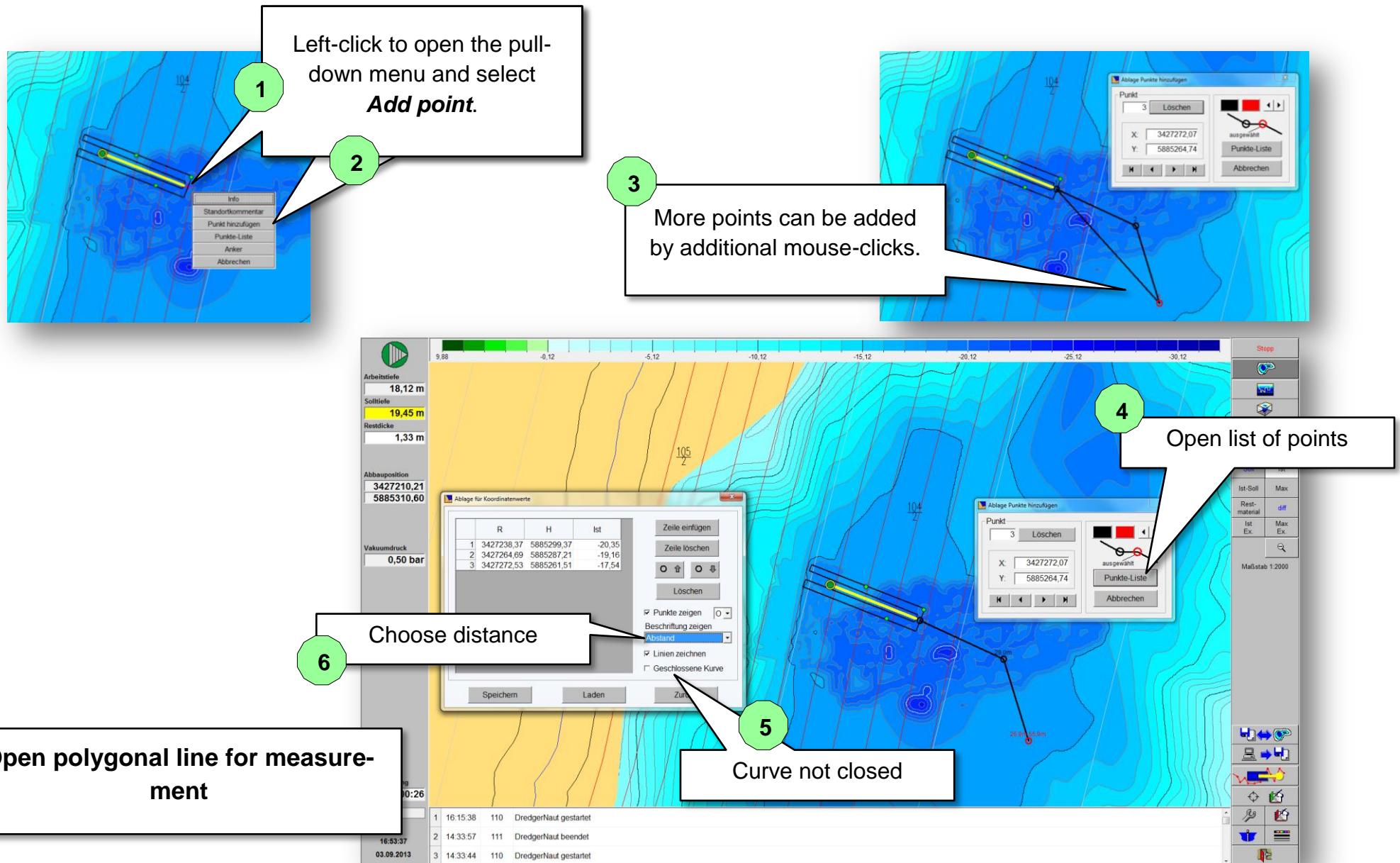
13.1 Creation of polygonal lines

In a lot of situations **DredgerNaut** offers the possibility to insert individual points or polygonal lines by means of the clipboard. This tool, at the same time, comprises measuring and export functions.



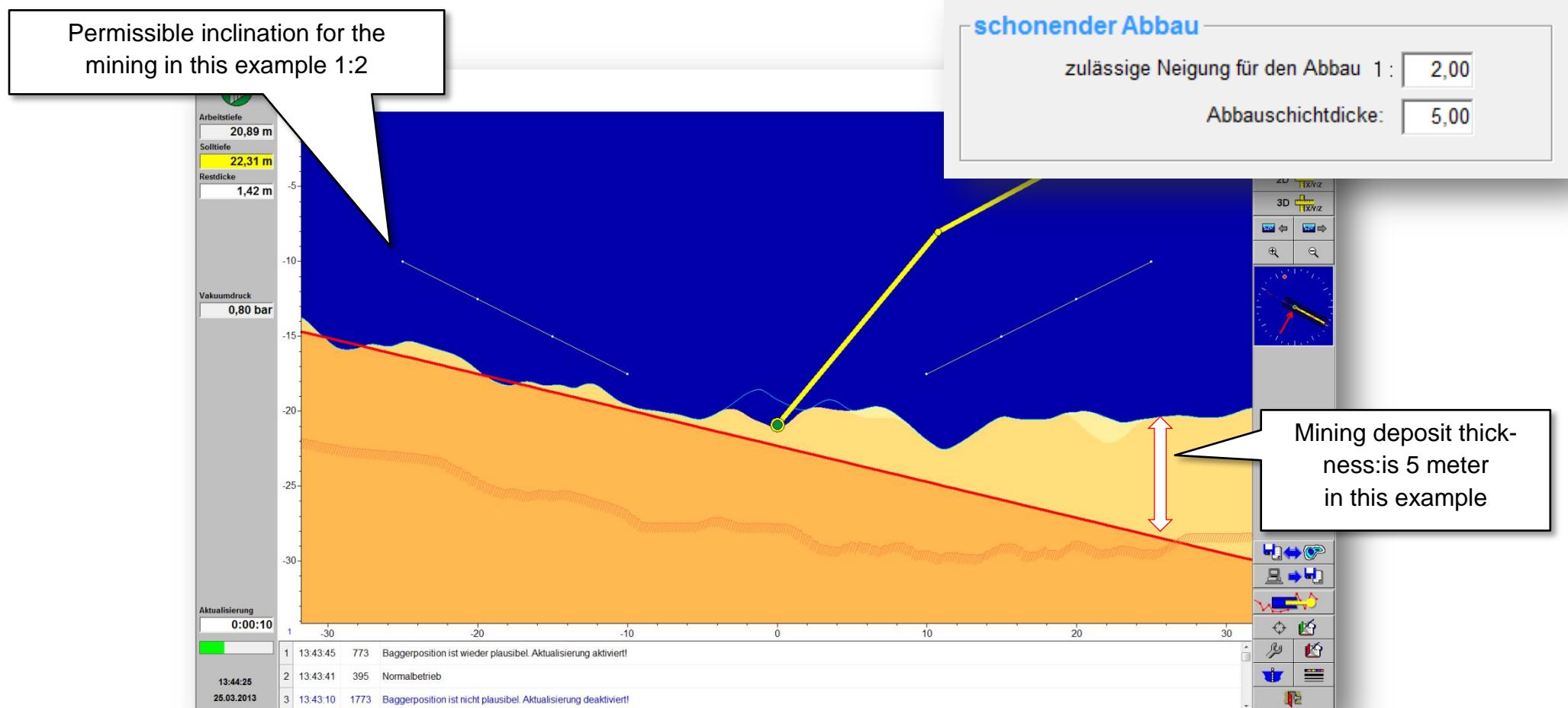
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14 Sensible mining

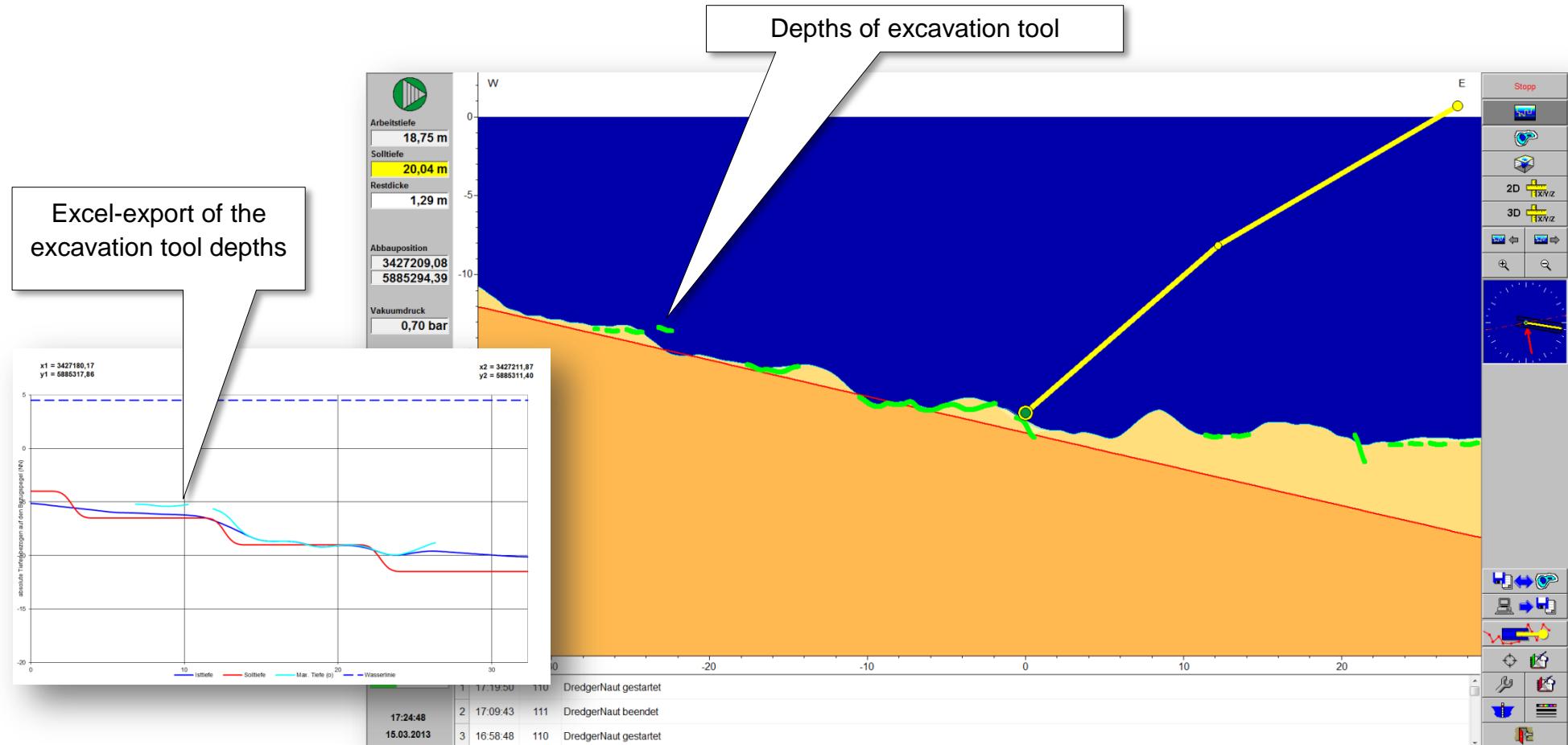
The function „sensible mining“ will assist the operator in the creation of permissible slope inclinations. This function is not activated by default. The parameters of the sensible mining are adjusted inside AdminTool.



15 Tracking the excavation tool depth

The excavation tool (suction tube head, grab or the slack of a bucket chain) can be considered independent from the echo sounder values.

The settings for tracking the excavation tool can be adjusted inside AdminTool.

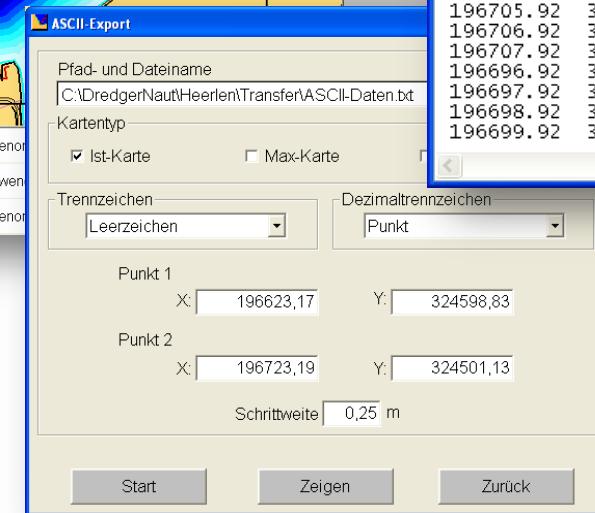
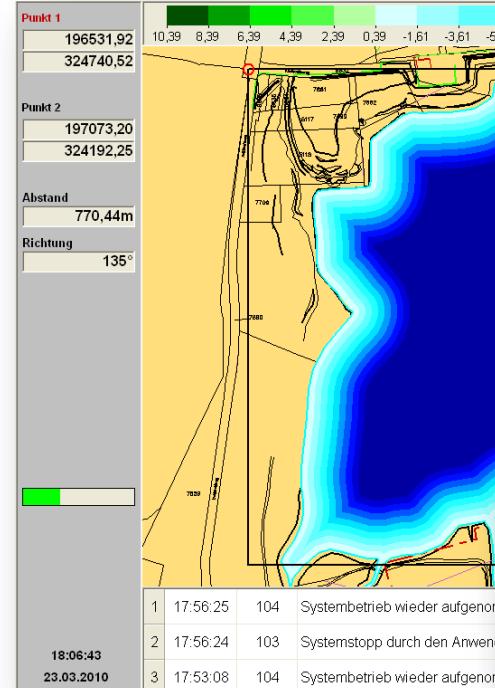


16 Data transfer

DredgerNaut offers the following possibilities to transfer data.

Functions

-  **Data-export**
-  **Data-import**
-  **Delete data**



ASCII-Daten.txt - Editor			
Datei	Bearbeiten	Format	Ansicht
196705.92	324686.52	89.19	
196702.92	324685.52	89.19	
196703.92	324685.52	89.17	
196704.92	324685.52	89.17	
196705.92	324685.52	89.18	
196706.92	324685.52	89.19	
196701.92	324684.52	89.20	
196702.92	324684.52	89.17	
196703.92	324684.52	89.15	
196704.92	324684.52	89.14	
196705.92	324684.52	89.15	
196706.92	324684.52	89.15	
196699.92	324683.52	89.24	
196700.92	324683.52	89.19	
196701.92	324683.52	89.16	
196702.92	324683.52	89.14	
196703.92	324683.52	89.12	
196704.92	324683.52	89.11	
196705.92	324683.52	89.11	
196706.92	324683.52	89.12	
196698.92	324682.52	89.22	
196699.92	324682.52	89.18	
196700.92	324682.52	89.15	
196701.92	324682.52	89.12	
196702.92	324682.52	89.11	
196703.92	324682.52	89.10	
196704.92	324682.52	89.09	
196705.92	324682.52	89.11	
196706.92	324682.52	89.13	
196707.92	324682.52	89.12	
196696.92	324681.52	89.30	
196697.92	324681.52	89.23	
196698.92	324681.52	89.18	
196699.92	324681.52	89.15	

Detailed informations are to be found inside
the manual **Documentation and data transfer**.

17 Documentation

DredgerNaut Manager offers the following possibilities for documentation.

Functions



Print



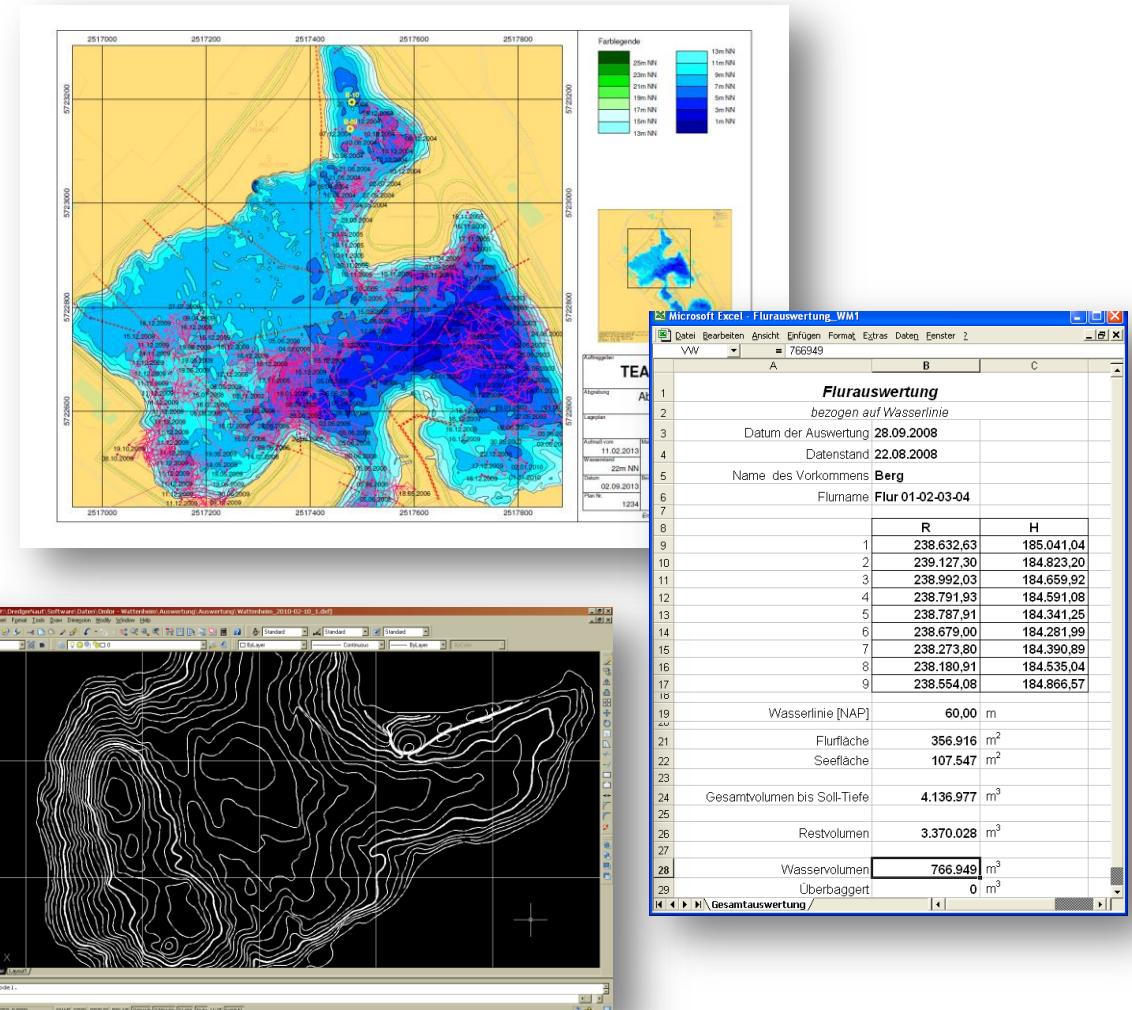
DXF-export



Excel intersections



Deposit assessment (calculation of volumes)



Detailed informations are to be found inside the manuals **Documentation and data transfer** and **Deposit assessment**.